

## Erratum: “Control of Flexible-Link Multiple Manipulators” [ASME J. Dyn. Syst., Meas., and Control, 124, No. 1, pp. 64–75]

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In the above paper, the vertical axis labels for Figs. 5, 6, and 7 were illegible. Corrected figures are provided below.

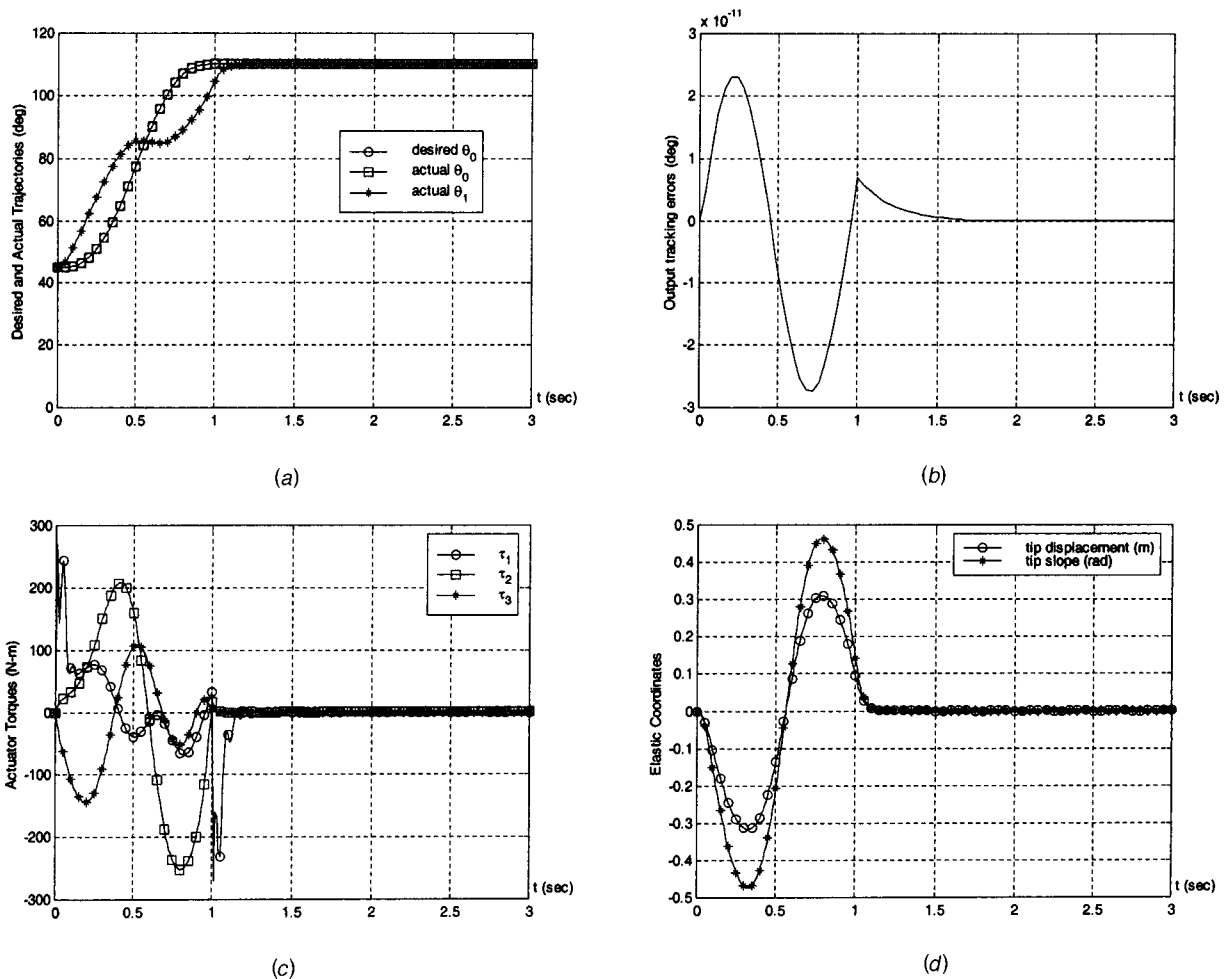
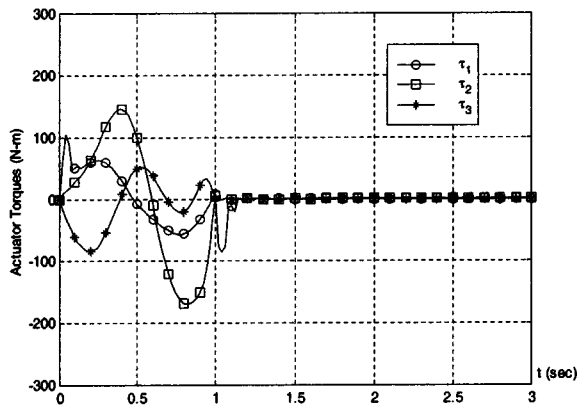
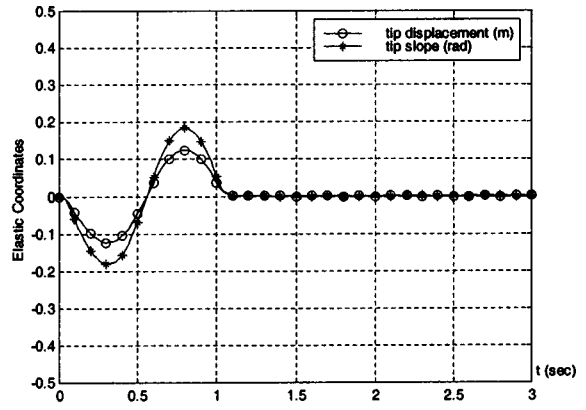


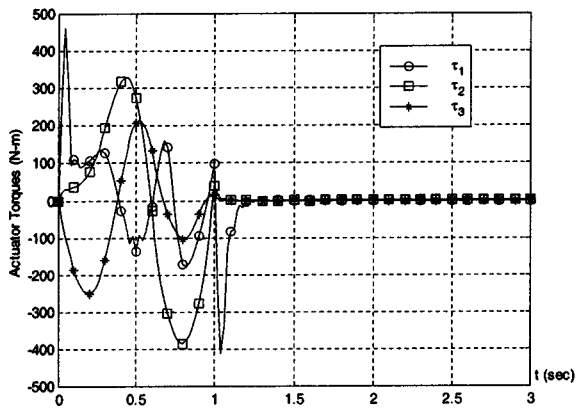
Fig. 5 Simulation results for case 1



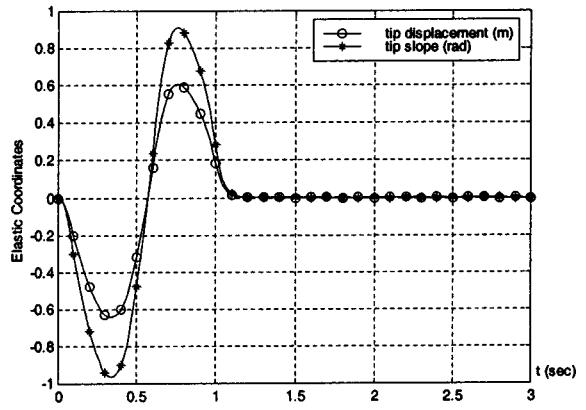
(a)



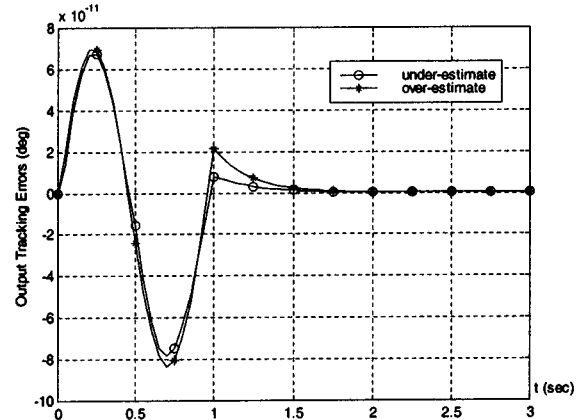
(b)



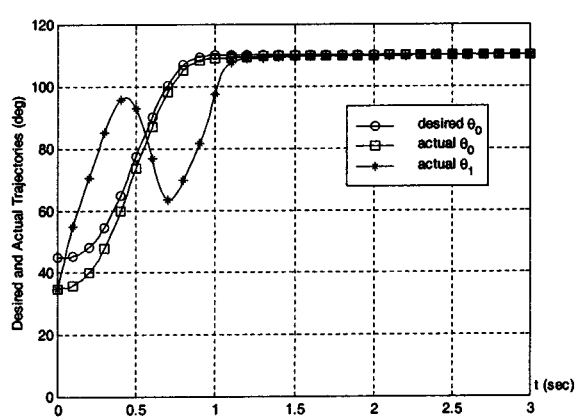
(c)



(d)

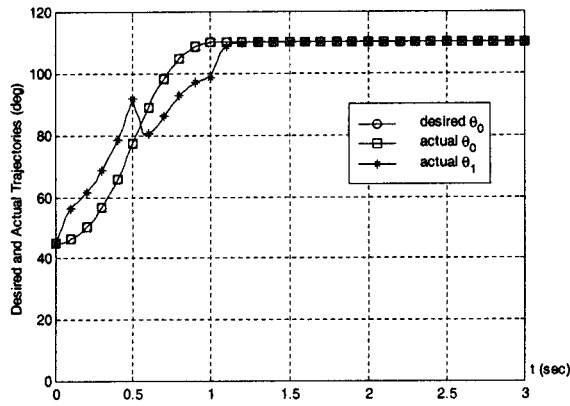


(e)

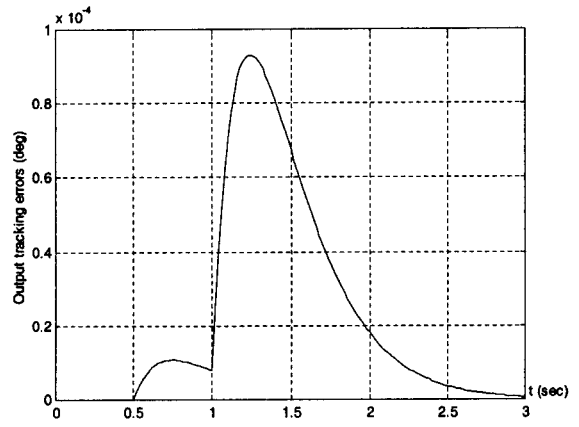


(f)

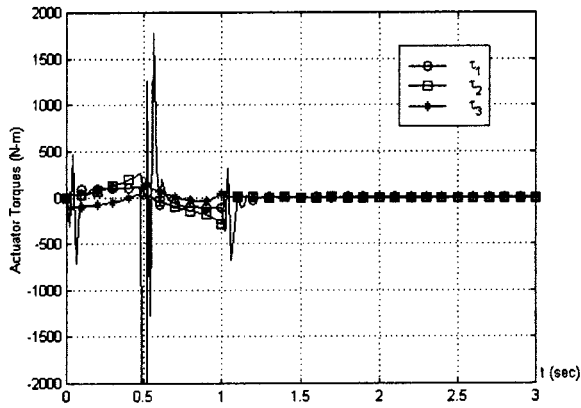
Fig. 6 Simulation results for case 2



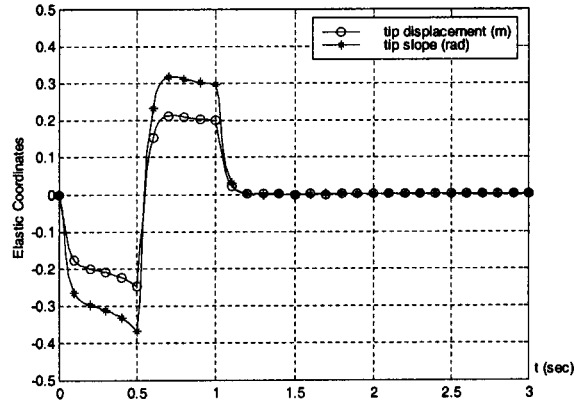
(a)



(b)



(c)



(d)

Fig. 7 Simulation results for case 3