A Mechanically Verified Verification Condition Generator

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Verification Condition Generator (VCG) tools have been effective in simplifying the task of proving programs correct. However, in the past these VCG tools have in general not themselves been mechanically proven, so any proof using and depending on these VCGs might not be sound. In our work, we define and rigorously prove correct a VCG tool within the HOL theorem proving system, for a standard while-loop language, with one new feature not usually treated: expressions with side effects. Starting from a structural operational semantics of this programming language, we prove as theorems the axioms and rules of inference of a Hoare-style axiomatic semantics, verifying their soundness. This axiomatic semantics is then used to define and prove correct a VCG tool for this language. Finally, this verified VCG is applied to an example program to verify its correctness.

1. INTRODUCTION

The most common technique used today to produce quality software without errors is testing. However, even repeated testing cannot reliably eliminate all errors, and hence is incomplete. To achieve a higher level of reliability and trust, programmers may construct proofs of correctness, verifying that the program satisfies a formal specification. This need be done only once, and eliminates whole classes of errors. However, these proofs are complex, full of details, and difficult to construct by hand, and thus may themselves contain errors, which reduces trust in the program so proved. Mechanical proofs are more secure, but even more detailed and difficult.

One solution to this difficulty is partially automating the construction of the proof by a tool called a Verification Condition Generator (VCG). This VCG tool writes the proof of the program, modulo a set of formulas called verification conditions which are left to the programmer to prove. These verification conditions do not contain any references to programming language phrases, but only deal with the logics of the underlying data types. This twice simplifies the programmer’s burden, reducing the volume of proof and level of proof, and makes the process more effective. However, in the past these VCG tools have not in general themselves been proven, meaning that the trust of a program’s proof rested on the trust of an unproven VCG tool.

In this work we define and rigorously prove correct a VCG within the Higher Order Logic (HOL) theorem proving system [Gordon 93], for a standard while-loop language that has a feature not usually treated: expressions with side effects. Expressions with side effects occur in the programming languages C and C++, and are therefore of practical interest. We prove that the truth of the verification conditions returned by the VCG suffice to verify the asserted program submitted to the VCG. This theorem stating the VCG’s correctness then supports the use of the VCG in proving the correctness of individual programs with complete soundness assured. The VCG automates much of the work and detail involved, relieving the programmer of all but the essential task of proving the verification conditions. This enables proofs of programs which are both effective and trustworthy.

2. PREVIOUS WORK

In this paper, we define a “verified” verification condition generator as one which has been proven to correctly produce, for any input program and specification, a set of verification conditions whose truth implies the consistency of the program with its specification. Preferably, this verification of the VCG will be mechanically checked for soundness, because of the many details and deep issues that arise. Many VCGs have been written but not verified; there is then no assurance that the verification conditions produced are properly related to the original program, and hence no security that after proving the verification conditions, the correctness of the program follows. Gordon’s work below is an exception in that the security is maintained by the HOL system itself.

In 1973 Larry Ragland verified a verification condition generator written in Nucleus, a language Ragland invented to both express a VCG and be verifiable [Ragland 73]. This was a remarkable piece of work,
well ahead of its time. The VCG system consisted of 203 procedures, nearly all of which were less than one page long, which gave rise to approximately 4000 verification conditions. The proof of the generator used an unverified VCG written in Snobol4. The verification conditions it generated were proven by hand, not mechanically, but substantially verified the VCG.

In 1975 Igarashi, London, and Luckham gave an axiomatic semantics for a subset of Pascal, and described a VCG they had written in MLISP2 [Igarashi 75]. The soundness of the axiomatic semantics was verified by hand proof, but the correctness of the VCG was not rigorously proven. The only mechanized part of this work was the VCG itself.

Michael Gordon in 1989 did the original work of constructing within HOL a framework for proving the correctness of programs [Gordon 89]. He introduced new constants in the HOL logic to represent each program construct, defining them as functions directly denoting the construct’s semantic meaning. This is known as a “shallow” embedding of the programming language in the HOL logic. The work included defining verification condition generators for both partial and total correctness as tactics. This approach yielded tools which could be used to soundly verify individual programs. However, the VCG tactic he defined was not itself proven. If it succeeded, the resulting subgoals were soundly related to the original correctness goal by the security of HOL itself. Fundamentally, there were certain limitations to the expressiveness and proven conclusions of this approach, as Gordon himself recognized:

P[\varepsilon/\nu] (substitution) is a meta notation and consequently the assignment axiom can only be stated as a meta theorem. This elementary point is nevertheless quite subtle. In order to prove the assignment axiom as a theorem within higher order logic it would be necessary to have types in the logic corresponding to formulae, variables and terms. One could then prove something like:

\forall \nu \exists E. \text{Spec}(\text{Truth}(\text{Subst}(P, E, \nu)),
\text{Assign}(\nu, \text{Value} E), \text{Truth} P)

It is clear that working out the details of this would be a lot of work. [Gordon 89]

In 1991, Sten Agerholm [Agerholm 92] used a similar shallow embedding to define the weakest preconditions of a small while-loop language, including unbounded nondeterminism and blocks. The semantics was designed to avoid syntactic notions like substitution. Similar to Gordon’s work, Agerholm defined a verification condition generator for total correctness specifications as an HOL tactic. This tactic needed additional information to handle sequences of commands and the while command, to be supplied by the user.

This paper explores the alternative approach described but not investigated by Gordon. It yields great expressiveness and control in stating and proving as theorems within HOL concepts which previously were only describable as meta-theorems outside HOL. For example, we have proven the assignment axiom described above:

\forall q \forall x. (q \land [x := e]) \land x := e \rightarrow q

where q \land [x := e] is a substituted version of q, described later.

To achieve this expressiveness, it is necessary to create a deeper foundation than that used previously. Instead of using an extension of the HOL Object Language as the programming language, we create an entirely new set of datatypes within the Object Language to represent constructs of the programming language and the associated assertion language. This is known as a “deep” embedding, as opposed to the shallow embedding developed by Gordon. This allows a significant difference in the way that the semantics of the programming language is defined. Instead of defining a construct as its semantic meaning, we define the construct as simply a syntactic constructor of phrases in the programming language, and then separately define the semantics of each construct in a structural operational semantics [Winskel 93]. This separation means that we can now decompose and analyze syntactic program phrases at the HOL Object Language level, and thus reason within HOL about the semantics of purely syntactic manipulations, such as substitution or verification condition generation, since they exist within the HOL logic.

This has definite advantages because syntactic manipulations, when semantically correct, are simpler and easier to calculate. They encapsulate a level of detailed semantic reasoning that then only needs to be proven once, instead of having to be repeatedly proven for every occurrence of that manipulation. This will be a recurring pattern in this paper, where repeatedly a syntactic manipulation is defined, and then its semantics is described and proven correct within HOL.

3. HIGHER ORDER LOGIC

Higher Order Logic (HOL) [Gordon 93] is a version of predicate calculus that allows variables to range over functions and predicates. Thus denotable values may be functions of any higher order. Strong typing ensures the consistency and proper meaning of all expressions. The power of this logic is similar to set theory, and it is sufficient for expressing most mathematical theories.

HOL is also a mechanical proof development system. It is secure in that only true theorems can be proved. Rather than attempting to automatically prove theorems, HOL acts as a supportive assistant, mechanically checking the validity of each step attempted by the user. It provides tools to define within the logic new types and constants, including primitive recursive functions, functions specified by properties, and relations defined by rule induction.
The primary interface to HOL is the polymorphic functional programming language ML ("Meta Language") [Cousineau 86]; commands to HOL are expressions in ML. Within ML is a second language OL ("Object Language"), representing terms and theorems by ML abstract datatypes term and thm. A shallow embedding represents program constructs by new OL functions to combine the semantics of the constituents to produce the semantics of the combination. Our approach is to define a third level of language, contained within OL as concrete recursive datatypes, to represent the constructs of the programming language PL being studied and its associated assertion language AL. We begin with the definition of variables.

4. VARIABLES AND VARIANTS

A variable is represented by a new concrete type var, with one constructor, \textsc{Var: string\to num\to var}. We define two deconstructor functions, \textit{Base} (\textit{VAR str n}) = \textit{str} and \textit{Index} (\textit{VAR str n}) = n. The number attribute eases the creation of variants of a variable, which are made by (possibly) increasing the number.

All possible variables are considered predefined of type \textit{num} (nonnegative integers). In future versions, we hope to treat other data types. Some languages distinguish between program variables and logical variables, which cannot be changed by program control. In this simple language, this is unnecessary. Our recent work with procedure calls supports logical variables.

The variant function has type \textit{var\to \langle \textit{var} \to \textit{str} \to \textit{var} \rangle}. \textit{Variant} \textit{x s} returns a variable which is a variant of \textit{x}, which is guaranteed not to be in the "exclusion" set \textit{s}. If \textit{x} is not in the set \textit{s}, then it is its own variant. This is used in defining proper substitution on quantified expressions.

The definition of \textit{variant} is somewhat deeper than it might originally appear. To have a constructive function for making variants in particular instances, we wanted

\[ (\cdot) \text{ variant } x \ s \]

\[ = (x \in s \Rightarrow \text{variant } (\text{mk variant } x 1) s \mid x) \]

where \textit{mk variant} (\textit{VAR str n}) \textit{k} = \textit{VAR str} (n + k). For any finite set \textit{s}, this definition of \textit{variant} will terminate, but unfortunately is not recursive. As a substitute, we wanted to define the \textit{variant} function by specifying its properties, as

1. (\textit{variant } x \ s) \text{ is variant } x ;
2. \sim (\textit{variant } x \ s \in s) ;
3. \forall z, \text{ if } (x \in \textit{variant } z \ s) \land \sim (z \in s) \\
then \textit{Index} (\textit{variant } x \ s) \leq \textit{Index} z ,

where we define

\[ y \text{ is variant } x \]

\[ = (\text{Base } y = \text{Base } x \land \text{Index } x \leq \text{Index } y) . \]

But the above specification did not easily support the proof of the existence theorem, that such a variant existed for any \textit{x} and \textit{s}, because the set of values for \textit{x} satisfying the third property's antecedent is infinite; we work strictly with finite sets. The solution was to introduce the function \textit{variant set}, where \textit{variant set } x \ n returns the set of the first \textit{n} variants of \textit{x}, all different from each other, so \textit{CARD} (\textit{variant set } x \ n) = n. Its definition is

\[ \text{variant set } x \ 0 = \{ \} ; \]

\[ \text{variant set } x \ (n + 1) = \{ \text{mk variant } x \ n \} \cup \text{variant set } x \ n . \]

Then by the pigeonhole principle, we are guaranteed that \textit{variant set } x ((\text{CARD } s) + 1) must contain at least one variable which is not in the set \textit{s}. This leads to the needed existence theorem. We then defined \textit{variant} with properties

1. \textit{variant } x \ s \in \textit{variant set } x ((\text{CARD } s) + 1) ;
2. \sim (\textit{variant } x \ s \in s) ;
3. \forall z, \text{ if } z \in \textit{variant set } x ((\text{CARD } s) + 1) \\
\land \sim (z \in s) \\
then \textit{Index} (\textit{variant } x \ s) \leq \textit{Index} z .

From this definition, we then proved both the original set of properties (1)-(3), and also the constructive function definition (\cdot) given above, as theorems.

5. PROGRAMMING AND ASSERTION LANGUAGES

The syntax of the programming language PL is

\begin{align*}
\text{exp}: & \quad e ::= n \mid x \mid +x \mid e_1 + e_2 \mid e_1 - e_2 \\
\text{bexp}: & \quad b ::= e_1 = e_2 \mid e_1 < e_2 \mid b_1 \land b_2 \mid b_1 \lor b_2 \mid \sim b \\
\text{cmd}: & \quad c ::= \text{skip} \mid \text{abort} \mid x ::= e \mid c_1 ; c_2 \\
& \quad \text{if } b \text{ then } c_1 \text{ else } c_2 \\
& \quad \text{assert } a \text{ while } b \text{ do } c
\end{align*}

Table 1: Programming Language Syntax

Most of these constructs are standard. \textit{n} is an unsigned integer; \textit{x} is a variable; \textit{+} is the increment operator; \textit{abort} causes an immediate abnormal termination; the while loop requires an invariant assertion to be supplied. The notation used above is for ease of reading; each phrase is actually formed by a constructor function, e.g., \textit{ASSIGN}: \textit{var\to exp\to cmd} for assignment.

The syntax of the associated assertion language AL is

\begin{align*}
\text{vexp}: & \quad v ::= n \mid x \mid v_1 + v_2 \mid v_1 - v_2 \mid v_1 \ast v_2 \\
\text{aexp}: & \quad a ::= \text{true} \mid \text{false} \mid v_1 = v_2 \mid v_1 < v_2 \\
& \quad \mid a_1 \land a_2 \mid a_1 \lor a_2 \mid \sim a \\
& \quad \mid a_1 \Rightarrow a_2 \mid a_1 = a_2 \mid a_1 \Rightarrow a_2 \mid a_3 \\
& \quad \mid \text{close } a \mid \forall x. a \mid \exists x. a
\end{align*}

Table 2: Assertion Language Syntax

Again, most of these expressions are standard. \textit{a_1} \Rightarrow \textit{a_2} \mid \textit{a_3} is a conditional expression, yielding the
value of \( a_2 \) or \( a_3 \) depending on the value of \( a_1 \), close \( a \) forms the universal closure of \( a \), which is true when \( a \) is true for all possible assignments to its free variables. The constructor function \( \textit{AVar} : \textit{var} \rightarrow \textit{vexp} \) creates a \( \textit{vexp} \) from a variable. We overload the same operator in different languages, asking the reader to disambiguate by context.

6. OPERATIONAL SEMANTICS

The semantics of the programming language is expressed by the following three relations. The values of all variables are in \textit{num} so a state is represented by a mapping from variables to \textit{num}.

\[ E \ e \ s_1 \ n \ s_2 : \ \text{numeric expression } e : \textit{exp} \text{ evaluated in state } s_1 \text{ yields numeric value } n : \textit{num} \text{ and state } s_2. \]

\[ B \ b \ s_1 \ t \ s_2 : \ \text{boolean expression } b : \textit{bexp} \text{ evaluated in state } s_1 \text{ yields truth value } t : \textit{bool} \text{ and state } s_2. \]

\[ C \ c \ s_1 \ s_2 : \ \text{command } c : \textit{cmd} \text{ evaluated in state } s_1 \text{ yields state } s_2. \]

Table 3 gives the structural operational semantics [Winskel 93] of the programming language PL, given as rules inductively defining the three relations \( E, B, \) and \( C \). These relations are defined within HOL using Tom Melham’s excellent rule induction package [Camilleri 92,Melham 92]. The notation \( s[v/x] \) indicates the state \( s \) updated so that \( (s[v/x])(x) = v \). This definition is straightforward, and is easy to read and analyze once the notation is understood.

Table 4 gives the semantics of the assertion language AL by recursive functions defined on the structure of the construct, in a directly denotational fashion.

\[ V \ v \ s : \ \text{numeric expression } v : \textit{vexp} \text{ evaluated in state } s \text{ yields a numeric value in } \textit{num}. \]

\[ A \ a \ s : \ \text{boolean expression } a : \textit{aexp} \text{ evaluated in state } s \text{ yields a truth value in } \textit{bool}. \]

7. SUBSTITUTION

We define proper substitution on assertion language expressions using the technique of simultaneous substitutions, following Stoughton [Stoughton 88]. The usual definition of proper substitution is a fully recursive function. Unfortunately, HOL only supports primitive recursive definitions. To overcome this, we use simultaneous substitutions, which are represented by functions of type \( \textit{subst} = \textit{var} \rightarrow \textit{vexp} \). This describes a family of substitutions, all of which are considered to take place simultaneously. This family is in principle infinite, but in practice all but a finite number of the substitutions are the identity substitution \( \iota \). The virtue of this approach is that the application of a simultaneous substitution to an assertion language expression may be defined using only primitive recursion, not full recursion, and then the normal single substitution operation of \( [v/z] \) may be defined as a special case:

\[ [v/z] = \lambda y. (y = z \Rightarrow v | \textit{AVar} y) \]

We apply a substitution by the infix operator \( \cdot \). Thus, \( a \cdot ss \) denotes the application of the simultaneous substitution \( ss \) to the expression \( a \), where \( a \) can be either \( \textit{vexp} \) or \( \textit{aexp} \). Therefore \( a \cdot [v/z] \) denotes the single substitution of the expression \( v \) for the variable \( z \) wherever \( z \) appears free in \( a \). Finally, there is a dual notion of applying a simultaneous substitution to a state, instead of an expression; this is called semantic substitution, and is defined as \( ss \cdot s = \lambda y. (V ss y) \).

Most of the cases of the definition of the application of a substitution to an expression are simply the distribution of the substitution across the immediate subexpressions. The interesting cases of the definition of \( a \cdot ss \) are where \( a \) is a quantified expression, for example:

\[ \forall z. a \cdot ss = \lambda \textit{free} = \bigcup_{x} \textit{FV}(a[s]) \forall y. (a \cdot (ss \cdot (\textit{AVar}(y)/x))). \]

Here \( \textit{FV} \) and \( \textit{FV} \), are functions that return the set of free variables in an \( \textit{aexp} \) or \( \textit{vexp} \) expression, and \( \textit{variant} x \cdot \textit{free} \) is a function that yields a new variable as a variant of \( x \), guaranteed not to be in the set \( \textit{free} \).

Once we have defined substitution as a syntactic manipulation, we can then prove the following two theorems about the semantics of substitution:

\[ \forall s ss. V (a \cdot ss) s = V \circ (s \cdot a \cdot ss) \]

\[ \forall s ss. A (a \cdot ss) s = A \circ (s \cdot a \cdot ss) \]

This is our statement of the Substitution Lemma of logic, and essentially says that syntactic substitution is equivalent to semantic substitution.

8. TRANSLATION

Expressions have typically not been treated in previous work on verification; there are some exceptions, notably Sokolowski [Sokolowski 84]. Expressions with side effects have been particularly excluded. Since expressions did not have side effects, they were often considered to be a sublanguage, common to both the programming language and the assertion language. Thus one would commonly see expressions such as \( p \wedge b \), where \( p \) was an assertion and \( b \) was a boolean expression from the programming language.

One of the key realizations of this work was the need to carefully distinguish these two languages, and not confuse their expression sublanguages. This then requires us to translate programming language expressions into the assertion language before the two may be combined as above. In fact, since we allow expressions to have side effects, there are actually two results of translating a programming language expression \( e \):
<table>
<thead>
<tr>
<th></th>
<th>Number</th>
<th>Variable</th>
<th>Increment</th>
</tr>
</thead>
<tbody>
<tr>
<td>E</td>
<td>(E(n) \equiv n)</td>
<td>(E(x) \equiv x)</td>
<td>(E(x) \equiv E(x))</td>
</tr>
<tr>
<td>Addition</td>
<td>(E(e_1 + e_2) \equiv E(e_1) + E(e_2))</td>
<td>(E(e_1 + e_2) \equiv E(e_1) + E(e_2))</td>
<td></td>
</tr>
<tr>
<td>Subtraction</td>
<td>(E(e_1 - e_2) \equiv E(e_1) - E(e_2))</td>
<td>(E(e_1 - e_2) \equiv E(e_1) - E(e_2))</td>
<td></td>
</tr>
<tr>
<td>Equality</td>
<td>(E(e_1 = e_2) \equiv E(e_1 = e_2))</td>
<td>(E(e_1 = e_2) \equiv E(e_1 = e_2))</td>
<td></td>
</tr>
<tr>
<td>Less Than</td>
<td>(E(e_1 &lt; e_2) \equiv E(e_1 &lt; e_2))</td>
<td>(E(e_1 &lt; e_2) \equiv E(e_1 &lt; e_2))</td>
<td></td>
</tr>
<tr>
<td>Conjunction</td>
<td>(E(b_1 \land b_2) \equiv E(b_1 \land b_2))</td>
<td>(E(b_1 \land b_2) \equiv E(b_1 \land b_2))</td>
<td></td>
</tr>
<tr>
<td>Disjunction</td>
<td>(E(b_1 \lor b_2) \equiv E(b_1 \lor b_2))</td>
<td>(E(b_1 \lor b_2) \equiv E(b_1 \lor b_2))</td>
<td></td>
</tr>
<tr>
<td>Negation</td>
<td>(E(\neg b) \equiv \neg E(b))</td>
<td>(E(\neg b) \equiv \neg E(b))</td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>C</th>
<th>Skip</th>
<th>Conditional</th>
</tr>
</thead>
<tbody>
<tr>
<td>C</td>
<td>(c)</td>
<td>(b _s_T_s_2)</td>
</tr>
<tr>
<td>Assignment</td>
<td>(C_e = e)</td>
<td>(C_{(c_1 \land c_2)} s_3)</td>
</tr>
</tbody>
</table>

Table 3: Programming Language Structural Operational Semantics

<table>
<thead>
<tr>
<th>V</th>
<th>V n s = n</th>
</tr>
</thead>
<tbody>
<tr>
<td>V x s = s(x)</td>
<td></td>
</tr>
<tr>
<td>V (v_1 + v_2) s = (V v_1 s + V v_2 s)</td>
<td></td>
</tr>
<tr>
<td>(_________ treated analogously)</td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>A</th>
<th>A true s = T</th>
</tr>
</thead>
<tbody>
<tr>
<td>A false s = F</td>
<td></td>
</tr>
<tr>
<td>A (v_1 = v_2) s = (V v_1 s = V v_2 s)</td>
<td></td>
</tr>
<tr>
<td>(_________ treated analogously)</td>
<td></td>
</tr>
<tr>
<td>A (a_1 \land a_2) s = (A a_1 \land A a_2 s)</td>
<td></td>
</tr>
<tr>
<td>(_________ treated analogously)</td>
<td></td>
</tr>
<tr>
<td>A (\forall x. a) s = (\forall x. A a s[x])</td>
<td></td>
</tr>
<tr>
<td>A (\exists x. a) s = (\exists x. A a s[x])</td>
<td></td>
</tr>
</tbody>
</table>

Table 4: Assertion Language Denotational Semantics
an assertion language expression, representing
the value of e in the state "before" evaluation;
• a simultaneous substitution, representing the
change in state from "before" evaluating e to
"after" evaluating e.

For example, the translator for numeric expressions is
defined using a helper function \( VE1 : \text{exp} \to \text{subst} \to
(aexp \# \text{subst}) \) (where \( \# \) denotes Cartesian product):

\[
\begin{align*}
VE1(n) \ ss & = n, \ ss \ ("\text{", makes a pair}) \\
VE1(x) \ ss & = (ss \ x), \ ss \\
VE1(+ x) \ ss & = (ss \ x) + 1, \ ss[((ss \ x) + 1) / x] \\
VE1(e_1 + e_2) \ ss & = (VE1 e_1 \\
& \quad - \lambda v_1. (VE1 e_2 \\
& \quad - \lambda v_2 ss_2. (v_1 + v_2, ss_2))) \ ss \\
VE1(e_1 - e_2) \ ss & = (VE1 e_1 \\
& \quad - \lambda v_1. (VE1 e_2 \\
& \quad - \lambda v_2 ss_2. (v_1 - v_2, ss_2))) \ ss
\end{align*}
\]

where \( \lambda \) is a "translator continuation" operator, defined as

\[ (f \to k) \ ss = \text{let} (v, ss') = f \ ss \ \text{in} \ k \ ss'. \]

Then define

\[
\begin{align*}
VE e & = \text{fst} \ (VE1 e) \\
VE_{\text{state}} e & = \text{snd} \ (VE1 e)
\end{align*}
\]

where \( \text{fst} \) and \( \text{snd} \) select the elements of a pair. We can then prove that
these translation functions, as syntactic manipulations, are semantically correct, according to the following theorem:

\[
\vdash \forall \sigma_1 \Pi \ k_1 \Sigma \ p. \ ((E e \ \sigma_1 \ k_1) \\
\quad \land \ k_1 \leq \sigma_1 < (VE_{\text{state}} e))
\]

Similar functions are used to translate boolean expressions. We define the helper function \( AB \) and the main
translaction functions \( AB_1 \) and \( AB_{\text{state}}, \) and prove their correctness as

\[
\vdash \forall \sigma_1 \Pi \ k_1 \Sigma \ p. \ ((B b \ \sigma_1 \ k_1) \\
\quad \land \ k_1 \leq \sigma_1 < (AB_{\text{state}} b))
\]

These theorems mean that every evaluation of a program
language expression has its semantics completely captured by the two translation functions for its
kind. These are essentially small compiler correctness proofs.

As a byproduct, we may now define the simultaneous
substitution that corresponds to an assignment statement,
overriding the expression's state change with the
change of the assignment:

\[
[x := e] = (VE_{\text{state}} e) / x.
\]

9. AXIOMATIC SEMANTICS

The semantics of Floyd/Howard partial correctness formulae is defined in Table 5.

Given these formulae, we can now express the axiomatic semantics of the programming language (Table 6), and prove each rule as a theorem from the previous structural operational semantics.

The most interesting of these proofs was that of the while-loop rule. It was necessary to prove a subsidiary

lemma first, by the strong version of rule induction for
command semantics provided by Tom Melham's rule induction package. Strong induction allowed as inductive hypotheses instances of the command semantic relation \( C \) for "lower levels" in the relation built up by rule induction, as well as inductive hypotheses that those
tuples satisfied the lemmas.

Although we did prove analogous theorems as an axiomatic semantics for both the numeric and boolean
expressions in the programming language, it turned out that there was a better way to handle them
provided through the translation functions. Using these
translation functions, we may define functions to compute
the appropriate precondition to an expression, given the
postcondition, as

\[
\begin{align*}
\text{ae.pre e a} & = a < (VE_{\text{state}} e) \\
\text{ab.pre b a} & = a < (AB_{\text{state}} b)
\end{align*}
\]

We may now prove the condensed axiomatic semantics for expressions given in Table 7.

These precondition functions now allow us to revise
the rules of inference for conditionals and loops, as given in Table 8.

10. VERIFICATION CONDITION GENERATOR

We now define a verification condition generator for
this programming language. To begin, we first define a
definition function \( vcg1 \), of type \( \text{cmd} \to \text{aexp} \to \text{aexp} \), \( \text{aexp} \# \text{list} \). This function takes a command and a postcondition, and returns a precondition and a list of
verification conditions that must be proved in order to
verify that command with respect to the precondition and
postcondition. This function does most of the work
of calculating verification conditions.

\( vcg1 \) is called by the main verification condition
generator function, \( vcg \), with type \( \text{cmd} \to \text{aexp} \to \text{aexp} \), \( \text{aexp} \# \text{list} \). \( vcg \) takes a precondition, a command,
and a postcondition, and returns a list of the verification
conditions for that command. \( vcg1 \) and \( vcg \) are defined in Table 9, in which \( [\cdot] \) denotes the empty list
and \( \text{ampersand} \) (\&\) is an infix version of HOL's \( \text{APPEND} \) operator to join two lists.

The correctness of the VCG functions defined in Table
9 is established by proving the following theorems from the
axioms and rules of inference of the axiomatic semantics:

\[
\begin{align*}
\text{VCGL1.THM:} & \quad \vdash \forall q. \text{let} (p, h) = vcg1 c q \in \\
& \quad \text{(every close h \Rightarrow \{p\} c (q))} \\
\text{VCGL.THM:} & \quad \vdash \forall p c q. \text{every close (vcg p c q) \Rightarrow \{p\} c (q)}
\end{align*}
\]

every \( P \) list is defined in HOL as being true when for
every element \( x \) in the list \( \text{list} \), the predicate \( P \) is true
when applied to \( x \). Accordingly, every close \( h \) means
that the universal closure of every verification condition in
\( h \) is true.
\begin{align*}
\text{aexp: } & \{a\} = \text{close } a = \forall s. \ A a s \\
\text{exp: } & \{p\} e \{q\} = \forall n s_1 s_2. \ A p s_1 \land E e s_1 n s_2 \Rightarrow A q s_2 \\
\text{bexp: } & \{p\} b \{q\} = \forall t s_1 s_2. \ A p s_1 \land B b s_1 t s_2 \Rightarrow A q s_2 \\
\text{cmd: } & \{p\} c \{q\} = \forall s_1 s_2. \ A p s_1 \land C c s_1 s_2 \Rightarrow A q s_2
\end{align*}

Table 5: Floyd/Hoare Partial Correctness Semantics

\begin{align*}
\text{Skip: } & \{q\} \text{skip } \{q\} \\
\text{Abort: } & \{\text{true}\} \text{abort } \{q\} \\
\text{Assignment: } & \{p\} c_1 \{r_1\}, \ \{r_2\} c_2 \{q\} \\
\text{Conditional: } & \{p\} \text{if } b \text{ then } c_1 \text{ else } c_2 \{q\} \\
\text{Sequence: } & \{a \land AB(b)\} b \{p\} \\
\text{Iteration: } & \text{assert } a \text{ while } b \text{ do } \{q\}
\end{align*}

Table 6: Programming Language Axiomatic Semantics

\begin{align*}
\text{Numeric expression precondition: } & \text{Boolean expression precondition:} \\
\{\text{ae.pre } e \ q\} \ e \ {q} & \{\text{ab.pre } b \ q\} \ b \ {q}
\end{align*}

Table 7: Programming Language Expression Axiomatic Semantics

\begin{align*}
\text{Conditional: } & \{r_1\} c_1 \{q\}, \ \{r_2\} c_2 \{q\} \\
\text{Iteration: } & \{a \land AB(b) \Rightarrow \text{ab.pre } b \ p\} \\
& \{a \land \sim AB(b) \Rightarrow \text{ab.pre } b \ q\} \\
& \{p\} c \{a\} \\
& \{a\} \text{assert } a \text{ while } b \text{ do } c \{q\}
\end{align*}

Table 8: Programming Language Axiomatic Semantics (revisions)
These theorems are proven from the axiomatic semantics by induction on the structure of the command involved. This verifies the VCG. It shows that the \texttt{v cg} function is \textit{sound}, that the correctness of the verification conditions it produces suffice to establish the correctness of the annotated program. This does not show that the \texttt{v cg} function is \textit{complete}, that if a program is correct, then the \texttt{v cg} function will produce a set of verification conditions sufficient to prove the program correct from the axiomatic semantics [Cook 78]. However, this soundness result is quite useful, in that we may directly apply these theorems in order to prove individual programs partially correct within HOL, as seen in the next section.

11. EXAMPLE PROGRAMS

Given the \texttt{v cg} function defined in the last section and its associated correctness theorem, proofs of program correctness may now be partially automated with security. This has been implemented in an HOL tactic, called \texttt{V CG-TAC}, which transforms a given program correctness goal to be proved into a set of subgoals which are the verification conditions returned by the \texttt{v cg} function. These subgoals are then proved within the HOL theorem proving system, using all the power and resources of that theorem prover, directed by the user’s ingenuity.

As an example, we will take the quotient/remainder algorithm for integer division by repeated subtraction. The program to be verified, with the annotations of the loop invariant and pre- and postconditions, is shown in Table 10.

Since \(x0\) and \(y0\) do not appear in the program text, their values cannot be altered by the program. This specification means that if the program terminates, the final value of \(q\) must be the quotient of the division of \(x0\) by \(y0\), and \(r\) the remainder.

A transcript of the application of \texttt{V CG-TAC} to this problem is shown in Table 11. We have written a parser for the subject language, using the parser library in HOL, invoked using the delimiters "[" and "]". The partial correctness goal is parsed and converted into the abstract syntax form used internally. \texttt{V CG-TAC} then converts that goal into verification conditions in the Object Language of HOL.

These verification conditions are now each solved as a subgoal by normal HOL theorem proving techniques.

The Object Language variables involved in these verification conditions are constructed to have names similar to the original program variable names; if there is a non-zero variant number, it is appended to the variable name. Thus, if program variable \(x\) were changed to \(z\) in the example of Table 11, the verification conditions would be the same but with the OL variable \(z\) in place of \(x\).

The \texttt{V CG-TAC} tactic first applies the theorem \texttt{V CG-THM} to reason backwards from the program correctness statement to a goal invoking the \texttt{v cg} function. By the theorem, the proof of these verification conditions will establish the proof of the original program correctness statement.

The next step of \texttt{V CG-TAC} is to "execute" the various syntactic manipulation functions mentioned in the current goal by symbolically rewriting the goal using the definitions of the functions, including \texttt{v cg}, \texttt{v cg1}, translations, substitutions, and substitution application.
\{x_0 = x \land y_0 = y\} \\
\ r := x; \\
\ q := 0; \\
assert x_0 = q \ast y_0 + r \land y_0 = y \\
while \sim (r < y) do \\
\ r := r - y; \\
\ q := ++q \\
\ od \\
\{x_0 = q \ast y_0 + r \land r < y_0\}

Table 10: Quotient/Remainder Algorithm

```
#g [[ \{x_0 = x \land y_0 = y\} \\
# \ r := x; \\
# \ q := 0; \\
# assert x_0 = q \ast y_0 + r \land y_0 = y \\
# while \sim (r < y) do \\
# \ r := r - y; \\
# \ q := ++q \\
# \ od \\
# \{x_0 = q \ast y_0 + r \land r < y_0\} \\
# ]]];;
...
#e(VGC_TAC);;
OK..
3 subgoals
"!x_0 q y_0 r y.
((x_0 = (q \ast y_0) + r) \land (y_0 = y)) \land r < y ==> 
(x_0 = (q \ast y_0) + r) \land r < y0"

"!x_0 q y_0 r y.
((x_0 = (q \ast y_0) + r) \land (y_0 = y)) \land \sim r < y ==> 
(x_0 = ((q + 1) \ast y_0) + (r - y)) \land (y0 = y)"

"!x_0 x y_0 y.
(x_0 = x) \land (y_0 = y) ==> (x_0 = (0 \ast y_0) + x) \land (y0 = y)"

() : void
Run time: 80.3s
Intermediate theorems generated: 5643
```

Table 11: Transcript of Application of VGC_TAC to Q/R Algorithm
cause the rewriting process is done symbolically, instead of actually executing a program, it is relatively slow, but complete soundness is assured. This "execution" converts the invocation of the \texttt{vcg} function on the annotated program into the actual set of verification conditions that the \texttt{vcg} function returns.

Afterwards, the goal is left as a set of "constant" verification conditions in the assertion language. \texttt{VCG\_TAC} then uses the definitions of the semantics of the assertion language to rewrite these verification conditions into equivalent statements in the Object Language of HOL, using the definitions of \textit{close}, \textit{A}, and \textit{V}. In particular, all references to assertion variables \textit{L} in program states are converted to references to similarly-named OL variables. These verification conditions are then presented to the user as the necessary subgoals that need to be solved in order to complete the proof of the program originally presented.

12. FUTURE WORK

We are currently extending this work to include several more language features, principally mutually recursive procedures and concurrency. In addition, we are working on VCGs for \textit{total correctness}.

We have completed the extension of the work reported in this paper to include total correctness, using the same semantic specification style and requiring additions to the invariant assertions for while loops. Work on mutually recursive procedures requires many new concepts and techniques to define the semantics and perform verification conditions generator proofs. These include declarations of procedures, their collection into environments, their verification independence of actual use of the procedures, well-formedness conditions on programs, and the delicate issue of parameter passing. We have completed, in HOL, a mechanized proof of correctness of a partial correctness VCG for a language that includes mutually recursive procedures. This work used the semantic specification style of this paper, and required suitable assertions in procedure headings. Work is proceeding toward formulating and mechanically verifying a total correctness VCG for the same language.

In future versions we hope to treat other datatypes by embedding a type system within our programming language, and by introducing a more complex state and a static semantics for the language which performs type-checking. This would use HOL's built-in datatypes to support booleans, strings, lists, etc.

Concurrency raises a whole host of new issues, ranging from the level of structural operational semantics ("big-step" versus "small-step"), to dealing with assertions describing temporal sequences of states instead of single states, to issues of fairness. We believe that a proper treatment of concurrency will exhibit qualities of modularity and compositionality. \textit{Modularity} means that a specification for a process should state both (a) the assumptions under which it should operate, and (b) the task (or commitment) which it should meet, given those assumptions. \textit{Compositionality} means that the specification of a system of processes should be verifiable in terms of the specifications of the individual constituent processes.

13. SUMMARY AND CONCLUSIONS

The fundamental contribution of this work is the exhibition of a tool to ease the task of proving programs which is itself proven to be sound. This verification condition generator tool performs an automatic, syntactic transformation of the annotated program into a set of verification conditions. The verification conditions produced are themselves proven within HOL, establishing the correctness of the program within the same system wherein the VCG was verified.

This proof of the correctness of the VCG may be considered as an instance of a compiler correctness proof, with the VCG translating from annotated programs to lists of verification conditions. Each of these has its semantics defined, and the VCG correctness theorem closes the commutative diagram, showing that the truth of the verification conditions implies the truth of the annotated program.

The programming language and its associated assertions are represented by new concrete recursive datatypes. This implies that they are completely independent of other data types and operations existing in the HOL system, without any hidden associations that might affect the validity of proof. This requires substantial work in defining their semantics and in proving the axioms and rules of inference of the axiomatic semantics from the operational semantics. However, the deeply embedded approach yields great expressiveness, ductility, and the ability to prove as theorems within HOL the correctness of various syntactic manipulations, which could only be stated as meta-theorems before. These theorems encapsulate a level of reasoning which now does not need to be repeated every time a program is verified, raising the level of proof from the semantic level to the syntactic. But the most important part of this work is the degree of trustworthiness of this syntactic reasoning. Verification condition generators are not new, but we are not aware of any other proofs of their correctness to this level of rigor. This enables programs which are both trustworthy and effective.

REFERENCES


Camilleri 92: J. Camilleri and T. Melham, Reasoning with Inductively Defined Relations in the HOL Theorem


