

Erratum

“Discrete-Time Inverse Dynamics Control of Flexible Joint Robots,” by K. P. Jankowski and H. Van Brussel, published in the June issue of the JOURNAL OF DYNAMIC SYSTEMS, MEASUREMENT, AND CONTROL, Vol. 114, No. 2, pp. 229-233.

In the above mentioned paper, the figure labeled Fig. 1 should be replaced by the figure which is presented below.

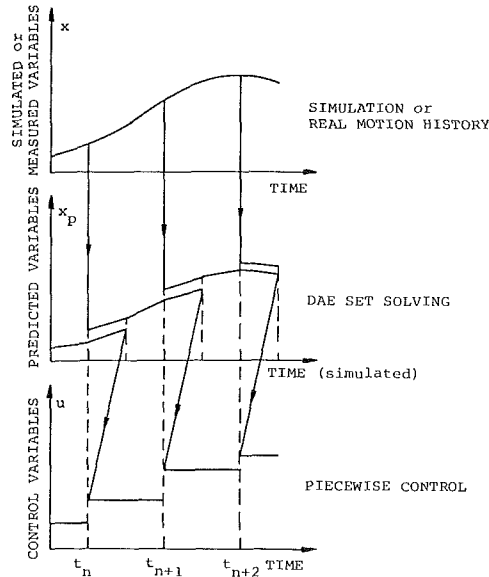


Fig. 1 Organization of the discrete-time control process