Novel cell segmentation and online SVM for cell cycle phase identification in automated microscopy

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ABSTRACT

Motivation: Automated identification of cell cycle phases captured via fluorescent microscopy is very important for understanding cell cycle and for drug discovery. In this article, we propose a novel cell detection method that utilizes both the intensity and shape information of the cell for better segmentation quality. In contrast to conventional off-line learning algorithms, an Online Support Vector Classifier (OSVC) is thus proposed, which removes support vectors from the old model and assigns new training examples weighted according to their importance to accommodate the ever-changing experimental conditions.

Results: We image three cell lines using fluorescent microscopy under different experiment conditions, including one treated with taxol. Then, we segment and classify the cell types into interphase, prophase, metaphase and anaphase. Experimental results show the effectiveness of the proposed system in image segmentation and cell phase identification.

Availability: The software and test datasets are available from the authors.

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Supplementary information: Supplementary data are available at Bioinformatics online.

1 INTRODUCTION

The knowledge of cell cycle progress, e.g. interphase, prophase, metaphase and anaphase, is important in understanding various diseases, notably cancer (Yan et al., 2006; Zhou and Wong, 2006). Changes in the cell cycle before and after drug use are useful for effective drug discovery research (Anderson et al., 2003; Baguley and Marshall, 2004; Dixon et al., 2002). Cell cycle progress can be identified by measuring changes in the nucleus as a function of time. Automated fluorescence microscopy imaging provides an important method to study nuclei dynamically and thus becomes an important quantitative technique in the fields of cell and systems biology (Chen et al., 2006; Harder et al., 2006; Wang et al., 2007; Yan et al., 2006; Zhou and Wong, 2006). Figure 1 (Fig. 4 in Wang et al., 2007) provides an example of cell mitosis process. Murphy et al. (Boland and Murphy, 2001; Boland et al., 1998; Chen and Murphy, 2006; Huang et al., 2003; Murphy et al., 2003) have proposed different feature extraction, feature reduction and classification algorithms for a similar problem of classification of subcellular location patterns in fluorescence microscope images. Although some methods have been proposed for cell cycle phase recognition (Chen et al., 2006; Gallardo et al., 2004), the automatic stratification of different phases of cells is still an unresolved issue in cell biology studies using fluorescence microscopy (Yan et al., 2006; Zhou and Wong, 2006). Along these lines, an automated system also based on the Support Vector Classifier (Charles et al., 2007; Harder et al., 2006) was proposed recently for classifying seven mitotic phases system. However, its classifier is updated in a ‘batch’ mode in contrast to our classifier’s ‘online’ mode. A context-based model (Wang et al., 2007) has been proposed to deal with this issue. However, its performance is highly dependent on the robustness of the tracking algorithm. When the cells are over-populated, the tracking algorithm becomes less reliable and the context information becomes less informative. Thus, it is important to develop a classification algorithm that is independent of the context information.

In this article, we present new segmentation and online learning algorithms to acquire and analyze cell cycle behaviors of a population of cells whose image is generated by microscopy. Here, online refers to the fact that the classifier will be continually updated by the misclassified samples to accommodate the ever-changing experimental conditions. Considering cells may cluster or overlap with each other, a novel cell detection algorithm is thus proposed. Figure 2 shows the detailed flowchart of the proposed segmentation method. First, cell shape information is obtained with a binarization process (Lindblad et al., 2004; Wahlby et al., 2002). Second, both intensity and shape information is used for local maxima generation. Finally, the local maxima (centers of cells) are detected inside the gradient vector field (the pixels will
Novel cell segmentation and online SVM

2 METHODS AND ALGORITHMS

2.1 Cell culture

HeLa H2B-GFP cells were thawed 6 days before plating for each experiment and cultured in DMEM with 10% FBS. Cells were incubated at 37°C in 5% CO2. All cells were plated in 8 well #1 German borosilicate sterile bottomed plates (Nalge Nunc International) 18 h before imaging at 25 000 cells per well (50 000 cells per ml). Untreated cells received medium while treated cells received 150 nm Taxol.

2.2 Image acquisition

Images were acquired on an automated epifluorescence TE2000-E Eclipse microscope (Nikon Instruments Inc., USA) with a motorized XYZ-plane stage. Light was from a mercury arc lamp with two neutral density filters. SimplePCI was used to control image acquisition. A custom designed microscope incubator set at 37°C was used to keep a constant environment while acquiring images. Representative fields were chosen and the starting X, Y and Z coordinates were used to seed the focusing position. The microscope will refine the focusing position by itself at the first pass of every 10 passes to compensate for deviation from focusing. Images were acquired using a 0.2s exposure time, every 15 min for 50 h, giving a total of 200 images for each position, which were then exported from SimplePCI as 16 bit uncompressed TIFF files to a 7TB network attached storage (NAS) arrays for processing with CellIQ.

2.3 Image segmentation and tracking

Image segmentation quality directly affects the tracking and cell phase recognition performance. Herein, we propose a cell segmentation method that consists of three major steps: binarization, cell detection and seeded watershed-based segmentation. Each step generates the input images for the next step. Figure 2 gives a detailed flowchart of the proposed segmentation method. Cell detection is the most important step, and generates the ‘seeds’ image of the seeded watershed algorithm, thereby determining the segmentation results.
2.3.1 Binarization To generate the binary image for the distance transform (Breu et al., 1995), we need to separate the cells from the background. It is well known the global threshold cannot generate good binary image when the intensity of background is uneven. Herein, we propose a binarization process using an adaptive thresholding method that based on the fact that there is an obvious intensity jump between the background and the object. We employ a data-driven background correction algorithm (Lindblad et al., 2004; Wahby et al., 2002) to estimate the background with cubic B-spline (Supplementary Material). We classify each pixel as part of the object if the difference between its intensity and that of the estimated background image is greater than a given threshold; otherwise, we classify it as part of the background.

2.3.2 Cell detection Local intensity maxima are often used in cell detection. The distance image obtained by applying the distance transform on the binary image gives the cells’ shape information. To utilize these two kinds of information, the original image is added to the distance image, which is formulated as: $I_1 = I_0 + a \Delta I_{\text{dis}}$, where $I_1$ is the new image, $I_0$ the original image and $\Delta I_{\text{dis}}$ the distance image obtained by applying the distance transform on the binary image. The parameter $a$ is experimentally set to 0.4. After that, the new image $I_1$ is filtered with Gaussian filtering, a good smoother, with SD $\sigma = 3$ (Steiger, 1998). In the filtered image, the noise is suppressed and the local maxima may correspond to the cell centers. Thus, the cell detection problem can be reduced to detecting local maxima in the filtered image.

It is well known that in the gradient vector field (GVF), the gradient vectors point to the local maxima. Analogous to the electron moving inside the electron field, we put one particle on each object pixel and allow the particles to move inside the GVF. To implement this process, given one particle at a pixel, we move the particle along the gradient vector of the pixel; if the gradient vector points to another pixel, the particle will move toward another pixel, while if the gradient vector points to the pixel itself, the particle will stay still. We repeat this process for each particle until the particles stop at the local maxima (Supplementary Material). To reduce the false local maxima, the gradient vector field is smoothed by a cubic B-spline technique with the parameter $\alpha$ set to 0.4. After that, the new image $I_2$ is filtered with Gaussian filtering, a good smoother, with SD $\sigma = 3$ (Steiger, 1998).

2.4 Feature extraction and feature selection

After obtaining the segmented nuclei, feature vectors are generated to represent the cells. Each feature vector contains 211 features. These features are composed of 10 general image features about shape, size and intensity (max intensity, min intensity, deviation of gray level, average intensity, length of long axis, length of short axis, area, perimeter) (Chen et al., 2006); 14 Haralick co-occurrence textural features (Haralick et al., 1973); 47 Zernike moment features (Boland and Murphy, 2001; Gallardo et al., 2004); 85 features generated by Gabor transformation (Manjunath and Ma, 1996; Zhou and Wong, 2006) and 54 shape features.

We develop one category of features. One kind of feature is based on the radii drawn at a series of 36 different angles (of 10 degrees each) through the centroid normalized by the nuclear perimeter, while the other consists of the 18 areas between each pair of radii normalized by the nuclear area. They are illustrated in Figure 4 (Supplementary Material). It is worth noting that the radii are drawn at a series of 36 different angles (of 10 degrees each) through the centroid normalized by the nuclear perimeter.

Finally, we obtain a shape descriptor with 54 elements and 4 have been used in the final feature subsets after feature selection.

To remove the irrelevant features and improve the performance of the learning system, a prediction risk-based feature selection method is employed to choose the sub-optimal feature sets (Guyon et al., 2002; Li et al., 2004). This method employs an embedded feature selection criterion of prediction risk, which evaluates features by calculating the change if the corresponding feature is replaced by its average value. It has several advantages. (1) The embedded feature selection model depends on learning machines. It can reach higher accuracy than the filter model, but it features lower computation complexity than the wrapper model. (2) The prediction risk criterion had been employed...
with several different learning machines (Li et al., 2004) and out-
performed Optimal Brain Damage (Guyon et al., 2002) when using
multi-class SVMs to test on more than 10 University of California
Irvine (UCI) datasets. (3) This method is easily implemented. Fifty-
eight features are kept for cell phase identification, comprised of 37
Gabor features, 1 geometric feature, 14 moment features, 2 texture
features and 4 shape features. The geometric feature used is ‘perimeter’.
Gabor features can describe the nuclear both in the time and frequency
domain. Thus so many Gabor features are kept. Figure 5 illustrates
the trends of the prediction accuracy while decreasing the number of
features used in the prediction algorithm.

2.5 Online support vector classifier

The basic idea of applying SVMs into interphase, prophase, metaphase
and anaphase can be outlined as follows. First, map the input vectors
into a feature space (possible with a higher dimension), either linearly
or non-linearly, which is relevant to the selection of the kernel function.
Then, within the feature space, seek an optimized linear division; i.e.
construct a hyper-plane that can separate the entire samples into two
classes (this can be extended to multi-classes) with the least errors and
anaphase can be outlined as follows. First, map the input vectors
Fig. 5. The trend of the prediction accuracy while increasing the feature
number.

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Then, within the feature space, seek an optimized linear division; i.e.
construct a hyper-plane that can separate the entire samples into two
classes (this can be extended to multi-classes) with the least errors and
maximal margin. The SVMs training process always seeks a global
optimized solution and avoids over-fitting, so it has the ability to deal
with a large number of features. A complete description of the theory
of SVMs for pattern recognition is given in the book by Vapnik (1998).

2.5.1 Problem formulation Given a set of \( l \) samples, i.e. a series
of input vectors \( x_i \in \mathbb{R}^d \) \((i = 1, \ldots, l)\), where \( x_i \) is the \( i \)th vector, and \( \mathbb{R}^d \) is
a Euclidean space with \( d \) dimensions. Suppose the output is expressed
by \( y_i \in \{+1, -1\} \) \((i = 1, \ldots, l)\), where the indexes \(-1\) and \(+1\) represent
respectively the two classes. The primal problem of SVM (Vapnik, 1998)
is given as following:

\[
\begin{align*}
\min_{\omega, b, \xi} & \quad \frac{1}{2} \omega^T \omega + C \sum_{i=1}^l \xi_i \\
\text{s.t.} & \quad y_i (\omega^T \phi(x_i) + b) \geq 1 - \xi_i \\
& \quad \xi_i \geq 0, i = 1, \ldots, l
\end{align*}
\]

where \( C \) is a constant, \( \xi_i \) are slack variables, \( b \) is the bias term, \( \omega \) is the weight
vector and \( \phi \) is a function that maps an example into the feature space.

We use the Lagrange multiplier method to solve the above optimization
problem:

\[
L(\omega, \xi, b, \alpha, \beta) = \frac{1}{2} \omega^T \omega + C \sum_{i=1}^l \xi_i - \sum_{i=1}^l \alpha_i (y_i (\omega^T \phi(x_i) + b) + \xi_i) - \beta \xi_i
\]

where \( \alpha_i \geq 0, \beta \geq 0, \delta \geq 0 \) are all Lagrange multipliers. Its dual problem
can thus be obtained:

\[
\begin{align*}
\max_{\alpha} & \quad D(\alpha) = \sum_{i=1}^l \alpha_i - \frac{1}{2} \sum_{i=1}^l \sum_{j=1}^l \alpha_i \alpha_j y_i y_j \cdot K(x_i, x_j) \\
\text{s.t.} & \quad 0 \leq \alpha_i \leq C, i = 1, \ldots, l \\
& \quad \sum_i \alpha_i y_i = 0
\end{align*}
\]

(3)

The gradient of \( D(\alpha) \) is denoted as \( g = (g_1, \ldots, g_l) \cdot g_k \) is calculated by:

\[
g_k = \frac{\partial D(\alpha)}{\partial \alpha_k} = y_k - \sum_i \alpha_i y_i K_{ij} = y_k - \hat{f}(x_k) + b
\]

(4)

where \( K_{ij} = K(x_i, x_j) \) is the kernel function, and \( \hat{f} \) is the predicted value.

In this article, the RBF kernel \( K(x_i, x_j) = \exp(-||x - x'||^2/\gamma) \) is used.
The decision function is given by:

\[
\hat{f}(x) = \text{sign} \left( \sum_{i=1}^l \alpha_i y_i K(x_i, x) + b \right)
\]

(5)

Various numerical algorithms have been developed to solve the SVM
QP problem (Platt et al., 1999; Vapnik, 1998). But all these algorithms
are supplied with data in batch and thus involve a large amount of
computation. Recently, various online SVM algorithms (Borders, 2005;
Kivinen et al., 2004; Lau and Wu, 2003) have been proposed to extend
the SVM to the online setting.

An online SVM training algorithm (LASVM) that can be used on
a large datasets. Borders (2005) presented a SVM algorithm called
LASVM. It tolerates smaller main memory and has a faster training
phase.

The standard online SVM algorithms are designed to handle binary
problem. Due to the ever-changing experimental conditions, the model
has to be updated continuously. The biologist hopes that after manually
labeling some misclassified samples, the classifiers can be updated
automatically and the result new model can be used to classify new
examples. However, to apply online SVM to the task of cell phase
identification, three factors have to be considered in advance. First,
the datasets are critically imbalanced. The classification accuracy will
undesirably bias toward the large classes. Second, some classes with
fewer samples are more important than those with larger training
samples. For example, prophase plays an important role in identifying
the starting point of the mitosis process, but there are only about 140
examples of prophase in 200 frames of microscope images. Last, this is
a multiclass classification problem.

2.5.2 Online support vector classifier Suppose we have one
previously trained model and a set of new examples, i.e. a series of input
vectors \( x_i \in \mathbb{R}^d \) \((i = 1, \ldots, l)\). The online learning will be discussed under
the framework proposed by Shalev-Shwartz and Singer (2006).

In the online setting, on trial \( t \), where \( t \in [1, L] \), the online learning
task can be regarded as solving the following optimization problem:

\[
\min_{\omega \in \mathbb{R}^d} P_t(\omega) = \frac{1}{2} \omega^T \omega + C \sum_{i=1}^l \xi_i
\]

(6)

with the first \( t-1 \) examples being \( \{x_1, y_1, \ldots, (x_{t-1}, y_{t-1})\} \).

Similarly, the dual objective function of \( P_t(\omega) \) is given by:

\[
D_t(\omega) = \sum_{i=1}^{t-1} \alpha_i - \frac{1}{2} \sum_{i=1}^{t-1} \sum_{j=1}^{t-1} \alpha_i \alpha_j y_i y_j \cdot K(x_i, x_j)
\]

(7)

From the definitions of \( D_t(\omega) \) and \( D(\omega) \), we can deduce that \( D_t(\alpha_{-t}) = D(\alpha_{-t}) \).
Thus, the online SVM can be treated as an incremental solver of the problem
\( \max_{\omega \in \mathbb{R}^d} D(\omega) \) s.t. \( W > \epsilon, \alpha_i = 0 \) (Shalev-Shwartz and Singer, 2006). It is worth noting that this problem
can be solved in the sequential manner. For example, on trial \( t \), \( D(\omega) \)
only depends only on the first \( t \) observed variables. Intuitively, the

larger the increase in the dual objective on each trail, the better the online SVC adjusts itself (Shalev-Shwartz and Singer, 2006).

Inspired by LASVM and the aforementioned framework, an online support vector is proposed for the problem of the cell phase identification. Three modifications are made. First, only the misclassified examples are used to update the model. Since new examples are critically imbalanced, the dominant class, i.e. interphase, will bring overwhelming information compared to other classes. Second, when trying to add a new example into the current support vector set, the coefficient $a_i$ is initialized with different weights according to the importance of each class (Shalev-Shwartz and Singer, 2006; Wang et al., 2005). Finally, the support vectors of the old model will be discarded once they become blatant non-support vectors during the optimization process. ‘One-Verse-One’ strategy is adopted to convert binary SVM to handle multiple classes (Vapnik, 1998).

We need to maintain four pieces of information: the set $S$ of potential support vector indices, the set $S_{old}$ of support vector indices that belong to the old model, the coefficients $a_i$ of the old kernel expansion and the partial derivative $g_i$. The procedures INSERTION and UPDATING are two basic blocks of OSVC (Online Support Vector Classifier).

The basic idea of OSVC can be formulated as below. (1) Load the previously trained model, (2) the procedure INSERTION attempts to insert the misclassified example into the current kernel expansion and (3) the procedure UPDATING updates the model.

**Algorithm (Online Support Vector Classifier)**

1. **Initialization:**
   Load the old support vector model. 
   $$S \leftarrow S_{old}, b \leftarrow b_{old}$$

2. **Online Iteration:**
   Set $\{x_k, y_k\}$, for $k = 1, 2, \ldots l$
   for $k = 1, \ldots , l$ do
     Obtain a new example $x_k = \{x_k, y_k\}$
     Compute $y = \sum_{i \in S} a_i y_i K(x_k, x_i) + b$
     if example $x_k$ is misclassified then
       INSERTION ($k$)
       UPDATING ($k$)
     end if
   end for

In INSERTION, the misclassified example $x_k$, $k \in S$ is inserted into the current support vector set. The coefficient $a_i$ is assigned with the preset values $C_p$ for positive example and $C_n$ for negative example (Shalev-Shwartz and Singer, 2006; Wang et al., 2005). The aims of assigning different weights are two fold. (1) The algorithm’s performance is also impaired when the training sets with uneven class sizes are used. When the class of interest only has limited training samples, its prediction accuracy will undesirably decrease. To solve this problem, we can assign greater weight to the class of interest and thus improve its accuracy. (2) When the experimental condition changes greatly, the new examples can be assigned with larger weights to reflect the changes in the experiment. The online adaptability of our algorithm can thus be improved. Then, a direction search will be performed to update the coefficients $a_i$ and $g_i$.

**INSERTION ($k$):**
Obtain a new example $x_k = \{x_k, y_k\}$
Compute $y = \sum_{i \in S} a_i y_i K(x_k, x_i) + b$
if example $x_k$ is misclassified then
  if $y_k = +1$ then
    $a_i \leftarrow C_p g_i, g_i \leftarrow y_k - \sum_{i \in S} a_i y_i K(x_k, x_i), S \leftarrow S \cup \{k\}$
    $i \leftarrow k, j \leftarrow \arg \min_{i \in S} g_i$ with $a_i < C_n$
  else
    $a_i \leftarrow C_n g_i, g_i \leftarrow y_k - \sum_{i \in S} a_i y_i K(x_k, x_i), S \leftarrow S \cup \{k\}$
    $i \leftarrow k, j \leftarrow \arg \max_{i \in S} g_i$ with $a_i < C_p$
end if
end if

If ($i, j$) is a $r$-violating pair
$$\lambda \leftarrow \min \left( \frac{g_i - g_j}{K_{ii} + K_{jj} - 2K_{ij}}, \frac{C_p - a_i C_n - a_j}{C_p} \right)$$
$$a_i \leftarrow a_i + \lambda, a_j \leftarrow a_j - \lambda$$
$$g_i \leftarrow g_i - \lambda(K_{ii} - K_{ij}) y_j$$
if end if

The procedure UPDATING keeps on searching the $r$-violating pair from the current support vector set and updating coefficients $a_i$ to increase the dual objective until there are no more such pairs. Analogous to REPROCESS in LASVM, the blatant non support vectors belonging to the old model will be removed (Borders, 2005).

**UPDATING ($k$):**
While there exists the $r$-violating pair ($i, j$) do
$$\lambda \leftarrow \min \left( \frac{g_i - g_j}{K_{ii} + K_{jj} - 2K_{ij}}, \frac{C_p - a_i C_n - a_j}{C_p} \right)$$
$$a_i \leftarrow a_i + \lambda, a_j \leftarrow a_j - \lambda$$
$$g_i \leftarrow g_i - \lambda(K_{ii} - K_{ij}) y_j$$
$$i \leftarrow \arg \max_{x \in S, g_i} a_i < C_p$$
$$j \leftarrow \arg \min_{x \in S, g_j} a_j < C_n$$
for each $a_i = 0$ and $s \in S_{old}$
if $y_i = -1$ and $g_i \geq g_j$, then $S = S - \{s\}$; end if
if $y_i = +1$ and $g_i \leq g_j$, then $S = S - \{s\}$; end if
if $b \leftarrow (g_i + g_j) / 2$
end for each
end while

### 3 RESULTS

#### 3.1 Segmentation

To test the segmentation algorithm, 240 images are used. This generates a test set consisting of 18 683 nuclei. Three approaches are tested. (1) Simple watershed algorithm without fragments merging (Vincent and Soille, 1991). (2) Watershed and hybrid merging algorithm (Yan et al., 2006). (3) The method proposed in this article. The hybrid merging algorithm can correctly identify 86% of the nuclei objects. Our proposed method, however, can correctly recognize 99% of the nuclei. Among the 18 683 nuclei, our method resulted in 35 nuclei that are over segmented and 154 nuclei that were under segmented. Most of the over segmentation is due to abnormal cell masses. The comparisons between these methods are given in Table 1. The details of segmentation validation are provided in the Supplementary Material.

#### 3.2 Cell phase identification

We use sensitivity and specificity as the measurements of our experimental results. Suppose TP, TN, FP and FN stand for the number of true positive, true negative, false positive and false negative samples, respectively, after the completion of cell phase identification. Sensitivity is defined as sensitivity = TP/(TP + FN), and specificity is defined as specificity = TN/(TN + FP). In other words, sensitivity is a statistical measure of how well classified the positive cells are while specificity reflects the ability to identify negative cells correctly.
We can calculate the sensitivity and specificity for each class if we treat one class as positive and the others as negative.

Three ‘movies’ are manually labeled for testing the OSVC algorithm, which correspond to three successive experiments with different experimental conditions. The first two movies are untreated and the third is treated with taxol. Each movie contains 240 images. SVM (Vapnik, 1998) and LASVM (Borders, 2005) are used as baseline algorithms. The second and third movies are each separated into two halves. The first halves are used as training sets and the second as testing sets. In the testing set of second movie, there are 9249 interphase cells, 71 prophase cells, 183 metaphase cells and 180 anaphase cells. In the second half of third movie, there are 13 930 interphase, 48 prophase cells, 539 metaphase cells and 225 anaphase cells. For the untreated case, SVM (Vapnik, 1998) is trained with the cells in the first movie and the first half of the second movie. For the LASVM and online SVC, the ‘old’ model is generated with the first movie while the first half of second movie is used to update the ‘old’ model with the proposed online learning algorithm. For the treated case, the combination of the first movie and third movie is used. This is in contrast to the untreated case, which needs the first and the second movie. It is worth nothing that the OSVC algorithm can be updated continuously and do not need to wait until hand-labeling half of the movie and then updating the classifier. In other words, if the user meets one misclassified sample, he can update the classifier immediately by recording this new sample and discarding the outdated support vectors. It is for the convenience of comparison that use the first half as the training set, since standard SVM (Vapnik, 1998) is updated in a “batch” mode. It is the parameters obtained with cross-validation test set, since standard SVM (Vapnik, 1998) is updated in a “batch” mode. It is the parameters obtained with cross-validation test set.

In weighted OSVC, the weights for interphase, prophase, metaphase and anaphase are 1, 30, 10 and 10, respectively. In Tables 2–5, the third rows of ‘OSVC weighted’ correspond to the weighted cases. In the non-weighted case, the \( C_p \) and \( C_n \) in \( \text{UPDATING} (k) \) are set to zero. Tables 2–5 show the sensitivity and specificity of both treated and untreated cases. Each line is an approach and each column is a phase. From Tables 2 and 3, the sensitivity of prophase with LASVM decreases while OSVC can increase the sensitivity greatly for both the untreated and treated case. In Table 5, the specificity of interphase can be improved significantly with weighted OSVC. The weights of OSVC can be tuned adaptively, which is useful when our focus is aimed at the classes having limited training samples. Here we give two general guidelines. (1) The more important cell types should be assigned greater weights. (2) At the initial stage, the weight for each class and the number of samples are in inverse proportion. For example, if the weight for prophase is 1 and the ratio between the numbers of prophase and metaphase is 10, then the weight for metaphase can be assigned 10.

### 4 DISCUSSION

Cells that undergo mitotic catastrophe will arrest, and eventually undergo apoptosis, before, during, or just after the metaphase-anaphase transition. Thus, we will detect these cells as frozen in metaphase or anaphase from image to image, allowing us to classify them as arrested metaphase.

Nuclei segmentation is an essential part of the whole system. To separate the dark nuclei from the background, a data-driven background correction algorithm is used as an adaptive thresholding method. In order to reduce the over-segmentation and under-segmentation problems, we first combine the shape...
information and intensity information of the nuclei together, and then the linear scale space theory is used to generate a local maximum that represents the position of one nucleus. Finally, the seeded watershed algorithm, in which the detected central points (positions of nuclei) are used as ‘seeds’, is used to segment the nuclei. The experimental results show that the proposed segmentation algorithm works well.

It is more challenging to deal with more irregular cell types, like U87-MG, which requires more robust segmentation method. But our system can work well even when such cells show up. The main aim of this research is to estimate the changes in the cell cycle before and after drug use. Prophase, interphase, metaphase and anaphase are the four cells types of our concern. The other cell types, like U87-MG, G0/G1, etc. seldom appear in our experiments and their lasting time are very short. So, we can use the context information to correct the errors caused by the incorrect segmentation. In addition, a more robust algorithm usually incurs more computational overhead, which is another important factor that must be considered in a real-time system. Therefore, we focus on improving the classification accuracy of these four cell types instead of employing a more complex segmentation method.

To solve the problem caused by imbalanced datasets, the weighted OSVC is proposed to improve the prediction accuracy of interest. For the untreated case, both the weighted and non-weighted OSVC perform better than SVM and LASVM. The weighted version can be applied when our focus is one particular class. In the treated case, only the weighted SVM can effectively improve the prediction accuracy of prophase due to the dramatic morphological changes of the treated cells. However, the weights for each class should be tuned to meet the real experimental requirements.

It is worth noting that the problems with unequal distribution of training examples can be solved by the ‘weighted’ SVM (Eitrich and Lang, 2006; Vapnik, 1998), which trains the SVMs by assigning the training samples with different cost weights according to class size. In the ‘weighted’ SVM, the prediction accuracy of prophase can be increased by 10–20% at the expense of slightly decrease of the classes with large samples using the reduced features. The weights for interphase, prophase, metaphase and anaphase are 1, 10, 10 and 10.

5 CONCLUSION AND FUTURE WORKS

In this article, a novel cell nuclei detection algorithm is proposed to work with watershed algorithms for cell nuclei segmentation of imaging for drug discovery and quantitative biology studies. Based on the segmentation results, an OSVC algorithm is used to classify the nuclei into different phases and the performance has been validated for the online cell phase identification. Future work is to construct a database from vast amounts of images of cancer cell lines under different drug perturbation conditions. Following this, the influence of various drug components in mitotic process will be analyzed to find the key anti-mitotic cancer drug components.

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