Extensions of criteria for evaluating risk prediction models for public health applications

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SUMMARY
We recently proposed two novel criteria to assess the usefulness of risk prediction models for public health applications. The proportion of cases followed, PCF(p), is the proportion of individuals who will develop disease who are included in the proportion p of individuals in the population at highest risk. The proportion needed to follow-up, PNF(q), is the proportion of the general population at highest risk that one needs to follow in order that a proportion q of those destined to become cases will be followed (Pfeiffer, R. M. and Gail, M. H., 2011. Two criteria for evaluating risk prediction models. Biometrics 67, 1057–1065). Here, we extend these criteria in two ways. First, we introduce two new criteria by integrating PCF and PNF over a range of values of q or p to obtain iPCF, the integrated PCF, and iPNF, the integrated PNF. A key assumption in the previous work was that the risk model is well calibrated. This assumption also underlies novel estimates of iPCF and iPNF based on observed risks in a population alone. The second extension is to propose and study estimates of PCF, PNF, iPCF, and iPNF that are consistent even if the risk models are not well calibrated. These new estimates are obtained from case–control data when the outcome prevalence in the population is known, and from cohort data, with baseline covariates and observed health outcomes. We study the efficiency of the various estimates and propose and compare tests for comparing two risk models, both of which were evaluated in the same validation data.

Keywords: Area under the receiver operator characteristics curve (ROC); AUC; Discrimination; Discriminatory accuracy; Risk models; Study design.

1. INTRODUCTION
Statistical models that predict disease incidence (Freedman and others, 2009), disease recurrence (Stephenson and others, 2006), mortality following disease onset (Albertsen and others, 2005), or response to treatment (O’Brien and others, 2011) are used in clinical practice and decision making, for example, to inform choices for a prevention or treatment with serious side effects. These models also have public health applications. They can be used to target preventive interventions to those with high enough risks to justify an intervention that has adverse effects and to identify high-risk individuals for intensive screening for early detection of disease.

We recently proposed two measures of concentration of risk that are directly relevant to public health decisions. We defined the “proportion of cases followed”, PCF(p), as the proportion of cases that would be followed in a program that followed the proportion p of the population at highest risk. We also proposed
a complementary criterion, the “proportion needed to follow-up”, PNF(q), namely the proportion of the general population at highest risk that one needs to follow in order that a proportion q of those destined to become cases will be followed. We also derived tests for comparing PCF and PNF for two risk models evaluated in the same validation data (Pfeiffer and Gail, 2011).

Here, we extend these criteria in two ways. In the previous work, p or q were prespecified and fixed numbers. First, we introduce two new criteria by integrating PCF and PNF over a range of values of p or q to obtain iPCF, the integrated PCF, and iPNF, the integrated PNF (Section 3). When integrating over the whole range of p and when the disease is rare, iPCF is similar to the area under the curve (AUC), the area under the receiver operating characteristic (ROC) curve (Pepe, 2003, p. 67). While the AUC is based on comparing ranks of the estimated risks in cases to those in non-cases, iPCF compares the risk in cases to risks in the whole population, which is a mixture of cases and non-cases. The AUC is ideal for measuring the discrimination accuracy in diagnostic applications, where one wants to distinguish cases from controls. For screening a general population, however, iPCF is more useful because it measures how different risks are in those destined to develop disease (or to have prevalent disease) from the population to be screened.

A key assumption in Pfeiffer and Gail (2011) was that the risk model is well calibrated. This assumption is also needed for novel estimates of iPCF and iPNF based on observed risks in a population alone (Section 4.1). The second extension is to propose and study estimates of PCF, PNF, iPCF, and iPNF that are consistent even if the risk model is not well calibrated. These new estimates are obtained from case–control data when the outcome prevalence in the population is known, and from cohort data, with baseline covariates and observed health outcomes (Sections 4.2 and 4.3). We propose testing differences between two risk models evaluated on the same dataset using iPCF and iPNF (Section 5). We then study the efficiency of the various estimates for these criteria and compare their performance for testing differences between two risk models evaluated on the same dataset in simulations (Section 6). A data example is presented in Section 7 before we close with a discussion (Section 8).

2. Notation and background

We are interested in predicting the probability of a binary event, \( Y = 1 \) or \( Y = 0 \). This event could denote the incidence of a particular disease over a given time period, for example, 5 years, or of dying before the end of a defined time interval after disease onset. The event could also refer to the response to a treatment in a population with a particular disease. Given a set of baseline predictors \( X \), a risk prediction model \( R(x) = P(Y = 1 \mid X = x) \) is a mapping from the set \( \Omega \) of possible values of \( X \) to \([0, 1]\). In a specific population, the distribution of the covariates \( F_X(x) \) induces the distribution \( F \) of risk \( R \) that has support on \([0, 1]\) through

\[
F(r) = P(R \leq r) = \int_{\{x: R(x) \leq r\}} dF_X(x).
\]  

(2.1)

We let \( G \) be the distribution of risk in those who experience the event (cases, \( Y = 1 \)),

\[
G(r) = P(R \leq r \mid Y = 1),
\]

and \( K \) be the distribution of risk in non-cases, or controls (\( Y = 0 \)),

\[
K(r) = P(R \leq r \mid Y = 0).
\]

We denote risk realizations from \( F \) by \( r^F \), and risk realizations from cases and non-cases by \( r^G \) and \( r^K \), respectively.
3. Criteria to assess model performance and their estimation

3.1 Review of the definition of PCF and PNF

We recently proposed and studied two criteria to assess the usefulness of models that predict the risk of disease incidence for screening and prevention, or the usefulness of prognostic models for management following disease diagnosis (Pfeiffer and Gail, 2011). The first criterion, the proportion of cases followed, PCF($p$) is the proportion of cases who are included in the proportion $p$ of individuals in the population at highest risk, given by

$$\text{PCF}(p) = 1 - G \circ F^{-1}(1 - p) = 1 - G(\phi_{1-p}),$$  \hspace{1cm} (3.1)

where $G \circ F(x) = G(F(x))$ is the composition of $G$ with $F$ and $\phi_{1-p} = F^{-1}(1 - p)$ denotes the $1 - p$th quantile of $F$. The second criterion is the proportion needed to follow-up PNF($q$) namely the proportion of the general population at highest risk that one needs to follow in order that a proportion $q$ of cases will be followed, defined as

$$\text{PNF}(q) = 1 - F \circ G^{-1}(1 - q) = 1 - F(\gamma_{1-q}),$$  \hspace{1cm} (3.2)

where $\gamma_{1-q} = G^{-1}(1 - q)$ denotes the $1 - q$th quantile of the distribution of risk in cases, $G$.

If risk is concentrated in a small proportion of the population at highest risk, then PCF($p$) will be high, even for small $p$ and PNF($q$) will be small, even for large $q$.

3.2 New criteria: $iPCF$ and $iPNF$

While PCF($p$) and PNF($q$) are useful criteria for model evaluation, they require the specification of thresholds $p$ and $q$. To lessen the dependency of these criteria on the given thresholds, we define the iPCF as

$$i\text{PCF}(p^*) = \int_{p^*}^{1} \text{PCF}(p) \, dW(p) = 1 - p^* - \int_{0}^{1-p^*} G(\phi_p) \, dW(p),$$  \hspace{1cm} (3.3)

where $W$ is a probability measure on the unit interval. The iPNF is

$$i\text{PNF}(q^*) = \int_{q^*}^{1} \text{PNF}(q) \, dW(q) = 1 - q^* - \int_{0}^{1-q^*} F(\gamma_q) \, dW(q).$$  \hspace{1cm} (3.4)

In what follows, we assume $dW(p) = dp$. In that case, using a change of variables, we obtain

$$i\text{PCF}(p^*) = 1 - p^* - \int_{0}^{\phi_{1-p^*}} G(u) \, dF(u) = 1 - p^* - \frac{1}{1 - p^*} P\{R_G \leq R_F \mid R_F \in (0, \phi_{1-p^*})\}$$  \hspace{1cm} (3.5)

and

$$i\text{PNF}(q^*) = 1 - q^* - \int_{0}^{\gamma_{1-q^*}} F(u) \, dG(u) = 1 - q^* - \frac{1}{1 - q^*} P\{R_F \leq R_G \mid R_G \in (0, \gamma_{1-q^*})\}.$$  \hspace{1cm} (3.6)

For the special case of $p^* = q^* = 0$, iPCF(0) = 1 − $P(R_G \leq R_F) = P(R_F < R_G)$ and iPNF(0) = 1 − $P(R_F \leq R_G) = P(R_F > R_G)$. We note that iPCF(0) is similar to the AUC, which can also be expressed as the probability that a randomly selected case has a higher projected risk than a randomly selected control, i.e. AUC = $P(R_G > R_K)$. While the AUC is based on comparing ranks of the estimated risks in cases to those in non-cases, iPCF(0) compares risk in cases to risks in the whole population, which is a mixture of cases and non-cases. However, for a rare disease $K \approx F$, and the values of the AUC and iPCF(0) will be close. Figure 1 shows a PCF curve when the population distribution of risk $F$ is a beta distribution with parameters $\alpha = 1.5$, $\beta = 28.5$, with $\mu \equiv P(Y = 1) = 0.05$. The area under this curve is iPCF(0) = 0.71.
Equations (3.5) and (3.6) resemble expressions for the partial area under the ROC curve (pAUC; McGlish 1989) that focuses on the region of the ROC curve with a low false positive rate, which is often of prime interest for diagnostic tests. Likewise, iPCF($p^*$) and iPNF($q^*$) can be used to focus on the high-risk portion of the population to be screened. However, (3.5) and (3.6) again use $F$ as the reference population instead of $K$.

4. Estimation of PCF($p$), PNF($q$), iPCF and iPNF

We now study estimates of PCF, PNF, and their integrated versions, iPCF and iPNF, for three types of data and derive their asymptotic distributions. First, we assume that the risk model is well calibrated, and a random sample of risk estimates $r^F_i$, $i = 1, \ldots, N$, is observed. We first review the estimators of PCF and PNF used in Pfeiffer and Gail (2011) for this setting and propose novel estimators for iPCF and iPNF. We then estimate PCF, PNF, iPCF, and iPNF non-parametrically using random samples of risks in cases, $r^G_i \sim G$, $i = 1, \ldots, m$, and controls, $r^K_j \sim K$, $j = 1, \ldots, n$, assuming the event probability $\mu \equiv P(Y = 1)$ in the population is known from external sources. We also study the corresponding estimates when a random sample of risks in the population and the associated binary outcomes $(r^F_i, Y_i)$, $i = 1, \ldots, N$, are available.

4.1 Estimation using observed risks in a population

If the risk model $R$ is well calibrated, that is, $P(Y = 1 \mid r) = r$, i.e. among individuals with risk $r$ the fraction of events is $r$, then $\mu \equiv P(Y = 1) = E(R) = \int_0^1 r \, dF(r)$, and the distributions $G$ and $K$ of risk in cases and non-cases, respectively, can be derived from the population distribution $F$ as

$$G(r) = P(R \leq r \mid Y = 1) = \frac{1}{\mu} \int_0^r t \, dF(t)$$

(4.1)
and
\[ K(r) = P(R \leq r \mid Y = 0) = \frac{1}{1 - \mu} \int_0^r (1 - t) \, dF(t). \tag{4.2} \]

In this setting, using (4.1),
\[ \text{PCF}(p) = 1 - G(\phi_{1-p}) = 1 - \frac{1}{\mu} \int_0^{\phi_{1-p}} t \, dF(t) = 1 - L(1 - p), \tag{4.3} \]
where the \( L \) denotes the Lorenz curve of \( F \) (Goldie, 1977), and
\[ \text{PNF}(q) = 1 - F(\gamma_{1-q}) = 1 - L^{-1}(1 - q), \tag{4.4} \]
where \( L^{-1} \) is the inverse of the Lorenz curve, also called the concentration curve (Goldie, 1977).

Thus, if the risk model is well calibrated, PCF and PNF can be estimated from a random sample \( r_1^F, \ldots, r_N^F \) of risks from the continuous distribution \( F \) in a given population. To briefly summarize earlier work (Pfeiffer and Gail, 2011), let \( r_{(1)}^F \leq \cdots \leq r_{(N)}^F \) denote the order statistics of the estimated risks, and \( \lfloor x \rfloor \) be the largest integer less than or equal to \( x \). Following Goldie (1977), and letting \( S_i = \sum_{k=1}^i r(k) \), an estimate of the Lorenz curve and thus PCF is
\[ \hat{\text{PCF}}(p) = 1 - L_N(1 - p) = 1 - S_{\lfloor N(1-p) \rfloor}/S_N. \tag{4.5} \]

Using the result of Goldie (1977) for the inverse function of the Lorenz curve, \( L_N^{-1} \), for a fixed value of \( 1 - q \), the PNF is estimated as
\[ \hat{\text{PNF}}(q) = 1 - L_N^{-1}(1 - q) = 1 - i/n, \quad S_i/S_N < 1 - q \leq S_{i+1}/S_N, \quad i = 0, \ldots, N. \tag{4.6} \]

By drawing on the distribution theory for the Lorenz curve and its inverse, we derived the asymptotic normality of the estimates in (4.5) and (4.6) and obtained their asymptotic variances using an influence function-based approach (Pfeiffer and Gail, 2011).

If the model is well calibrated, iPCF and iPNF also relate to the Lorenz curve and its inverse through
\[ \text{iPCF}(p^*) = 1 - p^* - \int_{p^*}^1 L(1 - p) \, dp \]
and
\[ \text{iPNF}(q^*) = 1 - q^* - \int_{q^*}^1 L^{-1}(1 - q) \, dq. \]

It is easy to see that a popular summary measure of the Lorenz curve, the Gini index (Gini, 1912), defined as \( \text{Gini} = 1 - 2 \int_0^1 L(p) \, dp \), which is commonly used to measure income inequality in economics, is related to iPCF(0) through \( \text{Gini} = 2\text{iPCF}(0) - 1 \).

Using ordered risk estimates \( r_{(1)}^F \leq \cdots \leq r_{(N)}^F \) in the population, a non-parametric estimate of iPCF based on (4.5) is thus obtained by interpolation as
\[ \hat{\text{iPCF}}(p^*) = 1 - p^* - \frac{1}{NS_N} \sum_{i=1}^{[(1-p^*)N]} S_i = 1 - p^* - \frac{1}{NS_N} \sum_{i=1}^{[(1-p^*)N]} \left( [(1 - p^*)N] - i + 1 \right) r_{(i)}. \tag{4.7} \]

For \( p^* = 0 \), this expression reduces to \( \hat{\text{iPNF}}(0) = 1 - 1/(NS_N) \sum_{i=1}^N (N - i + 1) r_{(i)} \).
Similarly, we estimate iPNF using simple geometric arguments as

\[
\hat{\text{iPNF}}(q^*) = 1 - q^* - \frac{1}{NSN} \sum_{i=1}^{k*} ir_{i+1},
\]  

(4.8)

where \(k^*\) satisfies \(S_{k^*}/S_N < q^* \leq S_{k^*+1}/S_N\).

In addition to being consistent, \(\hat{\text{iPCF}}\) and \(\hat{\text{iPNF}}\) also have asymptotically normal distributions. This follows directly from the fact that they are linear functionals of estimates of the Lorenz curve and its inverse, which are Gaussian stochastic processes (Goldie, 1977). The asymptotic variance estimates of \(\hat{\text{iPCF}}\) and \(\hat{\text{iPNF}}\) are given in Appendix A, see supplementary material available at Biostatistics online.

### 4.2 Estimation using risks in a case–control sample when \(\mu = P(Y = 1)\) is known

We assume that risks \(r_i^G \sim G, i = 1, \ldots, m,\) from a random sample of cases and risks \(r_j^K \sim K, j = 1, \ldots, n,\) from a random sample of non-cases from a population are available, and that the event probability \(\mu = P(Y = 1)\) in that population is known. We express the distribution of risk in the general population as \(F = \mu G + (1 - \mu)K\), and estimate \(F\) using the empirical distribution functions

\[
G_m(r^*) = \frac{1}{m} \sum_{i=1}^{m} I(r_i^G \leq r^*) \quad \text{and} \quad K_n(r^*) = \frac{1}{n} \sum_{i=1}^{n} I(r_i^K \leq r^*),
\]

as

\[
\hat{F}(r^*) = \mu G_m(r^*) + (1 - \mu)K_n(r^*).
\]

Plugging \(G_m\) and \(\hat{F}\) into (3.1) yields

\[
\hat{\text{PCF}}(p^*) = 1 - G_m \circ \hat{F}^{-1}(1 - p^*).
\]  

(4.9)

The expression for PNF in (3.2) simplifies to

\[
\hat{\text{PNF}}(q^*) = 1 - \mu(1 - q^*) - (1 - \mu)K \circ G^{-1}(1 - q^*)
\]

and thus

\[
\hat{\text{PNF}}(q^*) = 1 - \mu(1 - q^*) - (1 - \mu)K_n \circ G_m^{-1}(1 - q^*).
\]  

(4.10)

Using \(F = \mu G + (1 - \mu)K\) in (3.5), we express iPCF as

\[
i\text{PCF}(p^*) = 1 - p^* - \frac{\mu}{2} G^2(\phi_{1-p^*}) - (1 - \mu)P\{R_G \leq R_K; R_K \in (0, \phi_{1-p^*})\}.
\]  

(4.11)

We estimate iPCF using the empirical distribution functions \(G_m\) and \(K_n\), and \(\hat{F}\) and \(\hat{\phi}_{1-p^*} = \hat{F}^{-1}(1 - p^*)\) as

\[
i\text{PCF}(p^*) = 1 - p^* - \frac{\mu}{2} G^2_m(\phi_{1-p^*}) - (1 - \mu) \frac{1}{mn} \sum_{i,j} I(r_i^G \leq r_j^K; r_j^K \in (0, \phi_{1-p^*})},
\]  

(4.12)

where \(I(A)\) denotes the indicator function that is one if \(A\) is true and zero otherwise.
Similarly, iPNF given in (3.6) can be expressed as
\[ i\text{PNF}(q^*) = 1 - q^* - \mu \frac{1}{2} (1 - q^*)^2 - (1 - \mu) P\{R_K \leq R_G, R_G \in (0, \gamma_{1-q^*})\}, \]  
and thus an estimate is given by
\[ \hat{i}\text{PNF}(1 - q^*) = 1 - q^* - \mu \frac{1}{2} (1 - q^*)^2 - (1 - \mu) \frac{1}{mn} \sum_{i,j} I\{r_i^K \leq r_j^G; r_j^G \in (0, \hat{\gamma}_{1-q^*})\}, \]
where \( \hat{\gamma}_{1-q^*} = G_m^{-1}(1 - q^*) \).

Consistency of iPCF \((p^*)\) and \(i\text{PNF}\) follows immediately from the consistency of \(G_m\) and \(\hat{\phi}_{1-p^*}, \hat{\gamma}_{1-q^*}\) and the fact that \(E I\{r_i^G \leq r_j^K; r_j^K \in (0, \hat{\phi}_{1-p^*})\} = P\{R_G \leq R_K, R_K \in (0, \phi_{1-p^*})\}\) and \(E I\{r_i^K \leq r_j^G; r_j^G \in (0, \hat{\gamma}_{1-q^*})\} = P\{R_K \leq R_G, R_G \in (0, \gamma_{1-q^*})\}\).

PCF, PNF, iPCF, and iPNF are functionals of the two distribution functions \(G\) and \(K\) that are estimated based on independent samples. We derive their asymptotic properties using a bivariate influence function approach (Pires and Branco, 2002) in Appendix B, see supplementary material available at Biostatistics online.

### 4.3 Estimation using risks and outcomes in a population

Here, a random sample of risks and the corresponding event outcomes in a population are available, that is, we observe the i.i.d. samples \((r_i^F, Y_i), i = 1, \ldots, N\). For a model that predicts disease incidence, these data would be comprised of risk estimates at baseline and observed outcomes at the end of the follow-up period, and for a model that predicts the prevalence of a disease, the risks and outcomes could be based on a cross-sectional sample.

We estimate PCF and PNF by plugging estimates of \(F, G\) and the corresponding quantiles \(\phi\) and \(\gamma\) into the expressions (3.1) and (3.2), respectively. The distribution of risk in the general population, \(F\), is estimated using the empirical distribution function in the whole population,

\[ F_N(r^*) = \frac{1}{N} \sum_{i=1}^{N} I\{r_i^F \leq r^*\}, \]

and \(G\) is estimated using the empirical distribution function among cases,

\[ \hat{G}(r^*) = \frac{1}{NY} \sum_{i=1}^{N} I\{r_i^F \leq r^*, Y_i = 1\} = \frac{1}{\hat{n}_1} \sum_{i=1}^{\hat{n}_1} I\{r_i^G \leq r^*\}, \]

where \(Y = \sum Y_i / N\) denotes the empirical mean of \(Y\) and \(\hat{n}_1 = \sum Y_i\). Estimates of iPCF and iPNF are obtained in a similar way as

\[ \hat{i}\text{PCF}(p^*) = 1 - p^* - \frac{1}{N\hat{n}_1} \sum_{i,j} I\{r_i^G \leq r_j^F; r_j^F \in (0, \hat{\phi}_{1-p^*})\}, \]  
and
\[ \hat{i}\text{PNF}(q^*) = 1 - q^* - \frac{1}{N\hat{n}_1} \sum_{i,j} I\{r_i^F \leq r_j^G; r_j^G \in (0, \hat{\gamma}_{1-q^*})\}. \]  

The asymptotic distributions of the estimators for PCF, PNF, iPCF, and iPNF based on risks and outcomes in a cohort differ from the asymptotic distributions of the estimators (4.9)–(4.11) and (4.14) based on
the case–control data in the previous section, as they use different estimates of \( F \), and also incorporate the variation arising from estimating the disease prevalence and the number of cases, \( N\hat{Y} \), in the population. In Appendix C (see supplementary material available at Biostatistics online), we derive their asymptotic distributions by treating \( F \) and \( G \) as functions of the bivariate distribution function of \( (r^F, Y) \).

5. Comparing two risk models

We previously proposed test statistics based on PCF and PNF for two risk models, \( R^1 \) and \( R^2 \), both of which were applied to the same population. To test whether, for fixed \( p \), \( PCF^1 = PCF^2 \), or for a fixed \( q \), \( PNF^1 = PNF^2 \), we use the statistics

\[
T_{PCF}(p) = \frac{n(\hat{PCF}^1(p) - \hat{PCF}^2(p))^2}{\hat{V}_{PCF}} \quad \text{and} \quad T_{PNF}(q) = \frac{n(\hat{PNF}^1(q) - \hat{PNF}^2(q))^2}{\hat{V}_{PNF}},
\]

where \( \hat{V} \) are consistent estimates of the variance of the difference of the estimates.

Two new test statistics based on \( iPCF \) and \( iPNF \) to compare two models using correlated risk estimates \((r^1, r^2)\) are

\[
T_{iPCF}(p^*) = \frac{|iPCF^1(p^*) - iPCF^2(p^*)|^2}{\hat{V}_{iPCF}} \quad \text{and} \quad T_{iPNF}(q^*) = \frac{|iPNF^1(q^*) - iPNF^2(q^*)|^2}{\hat{V}_{iPNF}},
\]

where \( iPNF \) and \( iPCF \) for both models are evaluated at the same value \( p^* \) or \( q^* \), respectively.

Asymptotically all test statistics, \( T_{PCF}, T_{PNF}, T_{iPCF}, \) and \( T_{iPNF} \) have a central \( \chi^2 \) distribution under \( H_0 \). Under the alternative, the non-centrality parameters for the test statistics are

\[
\delta_{PCF} = n(PCF^1 - PCF^2)^2/V_{PCF}, \quad \delta_{PNF} = n(PNF^1 - PNF^2)^2/V_{PNF}, \quad \delta_{iPCF} = n(iPCF^1 - iPCF^2)^2/V_{iPCF}, \quad \delta_{iPNF} = n(iPNF^1 - iPNF^2)^2/V_{iPNF},
\]

respectively. The variances for all test statistics can be computed based on the respective influence functions \( \psi^{R_1} \) and \( \psi^{R_2} \) for models 1 and 2 as \( V = \text{Var}(\psi^{R_1} - \psi^{R_2}) \), or alternatively, using a bootstrap variance estimate. In the simulations, we use the bootstrap variances in the formulas of the test statistics.

6. Simulations

6.1 Efficiency of estimates of PCF, PNF, iPCF, and iPNF

We use simulations to investigate the properties of the non-parametric estimates of PCF, PNF, iPCF, and iPNF defined in Sections 4.1–4.3 and to compare their efficiency. We assume that the population distribution of risk is a beta distribution with parameters \( \alpha \) and \( \beta \), \( F(r) = B(r, \alpha, \beta)/B(\alpha, \beta) \), where \( B(r, \alpha, \beta) = \int_0^r t^{\alpha-1}(1-t)^{\beta-1} \, dt \) and \( B(\alpha, \beta) = B(1, \alpha, \beta) \). In this setting, the distributions of risk in cases and non-cases are also beta distributions, given by \( G(r) = B(r, \alpha + 1, \beta)/B(\alpha + 1, \beta) \) and \( K(r) = B(r, \alpha, \beta + 1)/B(\alpha, \beta + 1) \). The subscript \( R \) refers to estimates based on the population risks only, the subscript \( CC \) is used for estimates based on risks observed for a case–control sample with known disease prevalence \( \mu \), and the subscript \((R, Y)\) refers to estimates based on risks and observed outcomes in a population. The efficiency of the various estimates is compared using their asymptotic relative efficiencies (AREs), computed as the ratios of the influence function-based variances given in the Appendices (see supplementary material available at Biostatistics online).

To create data for each of the study designs, we first simulated risk estimates \( r_i^F, i = 1, \ldots, N \), and then generated the binary outcomes \( Y_i \) from a binomial distribution with probability \( r_i \), \( Y_i \sim \text{binom}(1, r_i) \), \( i = 1, \ldots, N \).
1, . . . , N. For the estimates using the population-based risks and the risks and outcomes, we used all the observations of \( r_i^F \) or \( (r_i^F, Y_i) \), respectively. To create a case–control study, we split the population into cases and non-cases and used the risk estimates from all the cases and all the non-cases together, with the true value of the disease prevalence \( \mu \). Thus, all estimates in a given simulation are based on the same observations.

Table 1 gives results for 500 simulations each based on a random sample of size \( N = 10000 \) for a rare disease. The beta distribution parameters were \( \alpha = 6.55, 1 \), and 0.3 with corresponding \( \beta = 124.45, 19.0 \), and 5.7 and expected risk \( \mu = E(R) = 0.05 \) for each \((\alpha, \beta)\) pair. The AUC values for these parameter choices are 0.63, 0.79, and 0.98, respectively, corresponding to models with moderate to very high discriminative ability. The mean estimates of PCF and PNF were very close to the theoretical values for all estimators. However, the estimates based on case–control data and cohort data with outcomes were much less precise than the corresponding estimates \( \hat{PCF}_R \) and \( \hat{PNF}_R \). The AREs of \( \hat{PCF}_{CC} \) compared with \( \hat{PCF}_R \) ranged from 22.86 to 387.2, with more loss of efficiency for parameter values corresponding to smaller AUCs. For example, for \( p = 0.20 \), \( ARE = 367.45 \) for \((\alpha, \beta) = (6.55, 124.45)\) and \( ARE = 22.86 \) for \((\alpha, \beta) = (0.3, 5.7)\). The AREs for the estimates based on risks and outcomes and based on case–control data were close to 1.00 in all cases. Estimates of PNF behaved very similarly to estimates of PCF in terms of efficiency (Table 1). Again, \( \hat{PNF}_{CC} \) and \( \hat{PNF}_{(R,Y)} \) were much less efficient than \( \hat{PNF}_R \) for all settings.

Supplementary material available at Biostatistics online, Table S1, gives results for a common disease, \( \mu = 0.30 \) with \( \alpha = 6.55, 1 \), and 0.3 and corresponding \( \beta = 15.28, 2.33 \), and 0.7, leading to the same AUC values as in Table 1. The patterns were very similar to those seen in Table 1, but the loss in efficiency for the case–control based estimates and for cohort data with outcome-based estimates was less pronounced than for a rare disease. \( \hat{PCF}_{CC} \) and \( \hat{PNF}_{CC} \) were somewhat more efficient than \( \hat{PCF}_{(R,Y)} \) and \( \hat{PNF}_{(R,Y)} \) for parameters resulting in larger AUC values. For example, for \( p = 0.10 \), the variance ratio of \( \hat{PCF}_{CC} \) compared with \( \hat{PCF}_{(R,Y)} \) was \( ARE = 3.43 \) for \((\alpha, \beta) = (0.3, 0.7)\).

Table 2 gives results for iPCF and iPNF for 500 simulations, each based on a random sample of size \( N = 10000 \) for the same simulation settings as in Table 1. Again, all methods had mean estimates that were very close to the theoretical values of iPCF and iPNF. Similar to PCF and PNF the estimates of iPCF and iPNF based on case–control data and \((R, Y)\) were much less precise than corresponding estimates \( \hat{iPCF}_R \) and \( \hat{iPNF}_R \). For \( \hat{iPCF}_{CC} \) compared with \( \hat{iPCF}_R \), the AREs ranged from 316.73 to 46.58 and were lower for parameter values corresponding to larger AUCs. For example, for \( p = 0.20 \), \( ARE = 311.36 \) for \((\alpha, \beta) = (6.55, 124.45)\) and \( ARE = 59.61 \) for \((\alpha, \beta) = (1, 2.33)\). Estimates of \( \hat{iPNF}_{CC} \) and \( \hat{iPNF}_{(R,Y)} \) were almost as efficient as \( \hat{PNF}_R \), but the loss of efficiency was less pronounced than for iPCF. \( \hat{iPCF}_{CC} \) and \( \hat{iPNF}_{CC} \) were slightly more efficient than estimated based on the cohort with outcomes. Results for iPCF and iPNF for a common disease are given in Table S2, see supplementary material available at Biostatistics online.

### 6.2 Comparing two risk models using PCF, PNF, and iPCF and iPNF

We examined the size and power of the tests (5.1) and (5.2) for comparing risk models 1 and 2 when PCF, PNF, iPCF, and iPNF are estimated from observed bivariate risks \((r_i^1, r_i^2)\), \(i = 1, \ldots, N\), and risks and outcomes in a population. To simulate bivariate risks with outcome data, we first drew a random number \( m \) of cases \((Y = 1)\) in a population of size \( N \) from a binomial distribution with parameter \( \mu \), and assigned the remaining \( n = N - m \) individuals to be controls \((Y = 0)\). To obtain risk estimates from each model that have a marginal beta distribution and are correlated, we first generated bivariate normal random variables \((X_{i1}, X_{i2}) \sim MVN((0, 0), \Sigma)\), \(i = 1, \ldots, N\), where \(\Sigma_{11} = \Sigma_{22} = 1\) and \(\Sigma_{12} = \Sigma_{21} = \rho\).

We then separately computed risks for the \( n \) cases and \( m \) controls from \( r_{i1} = F_1^{-1} \circ \Phi^{-1}(X_{i1}) \) and \( r_{i2} = F_2^{-1} \circ \Phi^{-1}(X_{i2}) \) where \( F_k^{-1}, k = 1, 2, \) denotes the inverse of the beta distribution function with parameters.
Table 1. Mean values of PCF and PNF estimated using observed risks $R$ in a population, assuming that the model is well calibrated; risk estimates in a case–control sampling when the disease prevalence $\mu$ is known, and based on observations of $(R, Y)$ in the population.

<table>
<thead>
<tr>
<th>$p$</th>
<th>PCF true</th>
<th>$\hat{PCF}$</th>
<th>var($\hat{PCF}$)</th>
<th>ARE</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>$R$</td>
<td>$CC$</td>
<td>$(R, Y)$</td>
<td></td>
</tr>
<tr>
<td>$\alpha = 6.55, \beta = 124.45$</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>0.10</td>
<td>0.18</td>
<td>0.18</td>
<td>0.18</td>
<td>0.01</td>
</tr>
<tr>
<td>0.20</td>
<td>0.32</td>
<td>0.32</td>
<td>0.31</td>
<td>0.31</td>
</tr>
<tr>
<td>0.30</td>
<td>0.44</td>
<td>0.44</td>
<td>0.44</td>
<td>0.44</td>
</tr>
<tr>
<td>0.40</td>
<td>0.55</td>
<td>0.55</td>
<td>0.55</td>
<td>0.55</td>
</tr>
</tbody>
</table>

| $\alpha = 1, \beta = 19$ | | | | |
| 0.10 | 0.32 | 0.32 | 0.32 | 0.32 | 0.06 | 3.80 | 3.81 | 59.41 | 59.64 | 1.00 |
| 0.20 | 0.51 | 0.51 | 0.51 | 0.51 | 0.08 | 4.60 | 4.61 | 59.27 | 59.39 | 1.00 |
| 0.30 | 0.65 | 0.65 | 0.65 | 0.65 | 0.07 | 4.30 | 4.31 | 62.52 | 62.70 | 1.00 |
| 0.40 | 0.76 | 0.76 | 0.76 | 0.76 | 0.05 | 3.53 | 3.53 | 68.18 | 68.19 | 1.00 |

| $\alpha = 0.3, \beta = 5.7$ | | | | |
| 0.10 | 0.51 | 0.51 | 0.51 | 0.51 | 0.22 | 4.23 | 4.32 | 19.07 | 19.48 | 1.02 |
| 0.20 | 0.73 | 0.73 | 0.73 | 0.73 | 0.16 | 3.65 | 3.71 | 22.48 | 22.86 | 1.02 |
| 0.30 | 0.86 | 0.86 | 0.86 | 0.86 | 0.08 | 2.35 | 2.38 | 28.20 | 28.46 | 1.01 |
| 0.40 | 0.93 | 0.93 | 0.93 | 0.93 | 0.03 | 1.28 | 1.29 | 38.74 | 38.98 | 1.01 |

<table>
<thead>
<tr>
<th>$q$</th>
<th>PNF true</th>
<th>$\hat{PNF}$</th>
<th>var($\hat{PNF}$)</th>
<th>ARE</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>$R$</td>
<td>$CC$</td>
<td>$(R, Y)$</td>
<td></td>
</tr>
<tr>
<td>$\alpha = 6.55, \beta = 124.45$</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>0.90</td>
<td>0.60</td>
<td>0.60</td>
<td>0.60</td>
<td>0.60</td>
</tr>
<tr>
<td>0.80</td>
<td>0.45</td>
<td>0.45</td>
<td>0.45</td>
<td>0.45</td>
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<tr>
<td>0.70</td>
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</tr>
<tr>
<td>0.60</td>
<td>0.26</td>
<td>0.26</td>
<td>0.26</td>
<td>0.26</td>
</tr>
</tbody>
</table>

| $\alpha = 1, \beta = 19$ | | | | |
| 0.90 | 0.60 | 0.60 | 0.60 | 0.60 | 0.06 | 6.11 | 6.15 | 95.58 | 94.83 | 0.99 |
| 0.80 | 0.45 | 0.45 | 0.45 | 0.45 | 0.06 | 4.52 | 4.54 | 74.24 | 74.62 | 1.01 |
| 0.70 | 0.34 | 0.34 | 0.35 | 0.35 | 0.05 | 3.34 | 3.36 | 62.44 | 62.80 | 1.01 |
| 0.60 | 0.26 | 0.26 | 0.26 | 0.26 | 0.04 | 2.42 | 2.43 | 59.11 | 59.46 | 1.01 |

| $\alpha = 0.3, \beta = 5.7$ | | | | |
| 0.90 | 0.35 | 0.35 | 0.38 | 0.38 | 0.11 | 3.58 | 3.65 | 32.19 | 32.81 | 1.02 |
| 0.80 | 0.25 | 0.25 | 0.26 | 0.26 | 0.08 | 1.89 | 1.93 | 24.23 | 24.75 | 1.02 |
| 0.70 | 0.18 | 0.18 | 0.19 | 0.19 | 0.05 | 1.14 | 1.14 | 21.79 | 21.79 | 1.00 |
| 0.60 | 0.13 | 0.13 | 0.14 | 0.14 | 0.04 | 0.71 | 0.72 | 20.15 | 20.33 | 1.01 |

Results are based on 500 simulations for each set of parameters $(\alpha, \beta)$ for the beta distribution and values of $q$ and $p$. Each simulation has $N = 10,000$ samples with $\mu = 0.05$. AREs are computed as the ratio of the influence function-based variances.

ARE = asymptotic relative efficiency, the ratio of the influence functions-based variances $CC/R = \text{var}(T_{CC})/\text{var}(T_R)$, $(R, Y)/R = \text{var}(T_{(R,Y)}/\text{var}(T_R)$, $(R, Y)/CC = \text{var}(T_{(R,Y)}/\text{var}(T_{CC})$, where $T = PCF$ or $T = PNF$, respectively.

†AUC = 0.63.
‡AUC = 0.79.
§AUC = 0.92.
Table 2. Mean values of iPCF and iPNF estimated using: the population risk distribution $F(R)$ assuming that the model is well calibrated; risks in a case–control study and known disease prevalence $\mu$; observations of $(R, Y)$ in the population

<table>
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<tr>
<th>$p^\dagger$ iPCF true</th>
<th>$\hat{R} \text{ iPCF}$</th>
<th>var($\hat{R}$ iPCF)</th>
<th>ARE</th>
</tr>
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<td>$\alpha = 6.55, \beta = 124.45^\dagger$</td>
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<td></td>
<td></td>
</tr>
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<td>0.60</td>
<td>0.60</td>
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<tr>
<td>0.40</td>
<td>0.48</td>
<td>0.48</td>
<td>0.48</td>
</tr>
<tr>
<td>$\alpha = 1, \beta = 2.33^\ddagger$</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>0.10</td>
<td>0.73</td>
<td>0.73</td>
<td>0.73</td>
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<td>0.20</td>
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</tbody>
</table>

<table>
<thead>
<tr>
<th>$q^\dagger$ iPNF true</th>
<th>$\hat{R} \text{ iPNF}$</th>
<th>var($\hat{R}$ iPNF)</th>
<th>ARE</th>
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</thead>
<tbody>
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<td>$\alpha = 6.55, \beta = 124.45^\dagger$</td>
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<td></td>
<td></td>
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<tr>
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<td>0.27</td>
<td>0.27</td>
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<td>0.22</td>
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<tr>
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<td>0.16</td>
<td>0.16</td>
</tr>
<tr>
<td>0.90</td>
<td>0.09</td>
<td>0.09</td>
<td>0.09</td>
</tr>
<tr>
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<td>0.07</td>
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<tr>
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<tr>
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<td>0.11</td>
<td>0.11</td>
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<tr>
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<tr>
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<td>0.08</td>
<td>0.08</td>
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<tr>
<td>0.90</td>
<td>0.05</td>
<td>0.05</td>
<td>0.05</td>
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</tbody>
</table>

Results are based on 500 simulations for each set of parameters $(\alpha, \beta)$ for the beta distribution and values of $q$ and $p$. Each simulation has $N = 10\,000$ samples with $\mu = 0.05$. AREs are computed as the ratio of the influence function-based variances.

ARE = asymptotic relative efficiency, the ratio of the influence functions-based variances $CC/R = \text{var}(T_{CC})/\text{var}(T_R)$, $(R, Y)/R = \text{var}(T(R, Y))/\text{var}(T_R)$, $(R, Y)/CC = \text{var}(T(R, Y))/\text{var}(T_{CC})$, where $T = \text{PCF}$ or $\text{T = PNF}$ respectively.

$^\dagger$AUC $= 0.63$.
$^\ddagger$AUC $= 0.79$.
$^\ddagger$AUC $= 0.92$.

$(\alpha_k + 1, \beta_k)$ for cases and parameters $(\alpha_k, \beta_k + 1)$ for controls, and $\Phi^{-1}$ is the inverse of the standard normal distribution.

Based on the random sample $(r_{1i}, r_{i2}, Y_i), \, i = 1, \ldots, N$, we computed the non-parametric estimates of $T_{\text{PCF}}, T_{\text{PNF}}, T_{\text{IPCF}},$ and $T_{\text{iPNF}}$ using observed risks only as well as risks and outcome data in the population,
with the bootstrap variance estimates based on $B = 500$ bootstrap samples. A standard way to assess the discriminatory ability of two models is to compare their AUC or partial area under the curve (pAUC) values. When the test statistics were estimated from risks and outcome data, we computed non-parametric estimates of pAUC,

$$\hat{\text{pAUC}}(p) = \frac{1}{mn} \sum_{i,j} I\{r_i^G > r_j^K, r_j^K \in (\bar{\phi}_{1-p}, 1)\} + 0.5I\{r_i^G = r_j^K, r_j^K \in (\bar{\phi}_{1-p}, 1)\},$$

and also used the test statistic

$$T_{\text{pAUC}} = \frac{\{\hat{\text{pAUC}}_1(p) - \hat{\text{pAUC}}_2(p)\}^2}{\text{var}(\hat{\text{pAUC}}_1 - \hat{\text{pAUC}}_2)}.$$

Estimates of size and power were based on 100 simulations for each choice of parameter values. Each simulation is based on a random sample of $N = 1000$ bivariate risks. We show results for $\rho = 0.2$ and a common disease, $\mu = 0.3$, as other choices resulted in similar conclusions.

Tests based on PCF, iPCF, PNF, or iPNF had better power than $T_{\text{pAUC}}$ for all settings in Table 3. Table 3 highlights again that estimates computed under the assumption of a well-calibrated model have better power than those relying on risks and outcome data. For example, for $(\alpha_1, \beta_1) = (1, 2.3)$ and $(\alpha_2, \beta_2) = (1.2, 2.8)$ the power ranged from 0.77 to 0.81 for iPCF$_R$, but was lower than 0.21 for iPCF$_{(R,Y)}$ for all values of $p$, and from 0.79 to 0.82 for iPNF$_R$, and from 0.29 to 0.77 for iPNF$_{(R,Y)}$; the power was lower for smaller values of $q$. Tests based on iPCF$_R$ and iPNF$_R$ had somewhat better power than tests based on PCF$_R$ and PNF$_R$.

7. Data example

To illustrate the various estimates of PCF, PNF, iPCF, and iPNF, we used data from a validation study of a colorectal cancer (CRC) risk prediction model (Freedman and others, 2009) that was developed to aid decision making for colorectal cancer screening. The risk model $R$ estimates the probability, or absolute risk (also called cumulative incidence), of the binary event defined as “developing CRC during the age interval $[a, b]$”, given that one is alive and free of CRC at age $a$”. Letting $T$ denote the failure time, the absolute CRC risk $R$ is

$$R(x, a, b) = P(T \in (a, b], \text{cause} = \text{CRC} \mid T > a) = \int_a^b h_{\text{CRC}}(t, x)e^{-\int_0^t h_{\text{CRC}}(u, x)+h_{\text{M}}(u, x) \, du} \, dt,$$

where $x$ denotes individual covariates, $h_{\text{CRC}}(t, x)$ is the cause-specific hazard for CRC, and $h_{\text{M}}(t, x)$ denotes the competing mortality hazard.

The validation data were from an independent sample of 108,057 women from a prospective cohort, the National Institutes of Health (NIH)-AARP Diet and Health Study (Park and others, 2009). For the $i$th woman in the validation cohort the starting age $a_i$ of the prediction was her age at entry into the cohort, and the end of the prediction interval, $b_i$, the age the woman had at the sooner of the end of study or loss to follow-up. Note that $b_i$ does not depend on whether the woman died or developed CRC. These events are accounted for in the calculation of absolute risk $R$. For the validation, we thus define the event as $Y_i = 1$ if woman $i$ develops CRC in $(a_i, b_i]$ and $Y_i = 0$ otherwise. The mean follow-up time was 6.9 years, and 965 women were diagnosed with CRC during follow-up. For estimates of PCF, PNF, iPCF, and iPNF based on case–control data, the disease prevalence $\mu$ was the observed incidence of CRC in the validation cohort.

Based on risk predictions for all 108,057 women in the study, $R$ had $\hat{\text{AUC}} = 0.605$. Estimates $\hat{\text{PCFCC}}$ and $\hat{\text{PCF}_{(R,Y)}}$ were basically identical, but the latter had slightly wider confidence intervals as the uncertainty from estimating $\mu$ is also accommodated (Table 4). For example, for $p = 0.10$, $\hat{\text{PCFCC}} = 0.178$ with
Table 3. Power of the tests $T_{pAUC}$, $T_{PCF}$, $T_{PNF}$, $T_{iPCF}$, and $T_{iPNF}$ for two beta-distributed risk models under the assumption of well-calibrated models, $R_1$ with parameters $(\alpha_1, \beta_1)$ and $R_2$ with parameters $(\alpha_2, \beta_2)$ for $q = 0.1$ for sample size $N = 1000$, with $\mu = 0.3$ and $c = \chi^2_{0.05} = 3.84$

<table>
<thead>
<tr>
<th>$p, q$</th>
<th>$pAUC$</th>
<th>$PCF$</th>
<th>$PNF$</th>
<th>$iPCF$</th>
<th>$iPNF$</th>
<th>$pAUC$</th>
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<th>$iPCF$</th>
<th>$PNF$</th>
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<tr>
<td>$(0.1, 0.9)$</td>
<td>0.06, 0.04</td>
<td>0.31, 0.29</td>
<td>0.44, 0.53</td>
<td>0.88, 0.84</td>
<td>0.95, 0.96</td>
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<td>0.89</td>
<td>1.00</td>
<td>0.94</td>
<td>1.00</td>
</tr>
<tr>
<td>$(0.2, 0.8)$</td>
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<td>0.56, 0.51</td>
<td>0.36, 0.40</td>
<td>0.93, 0.90</td>
<td>0.89, 0.91</td>
<td>0.92</td>
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</tr>
<tr>
<td>$(0.3, 0.7)$</td>
<td>0.23, 0.19</td>
<td>0.75, 0.67</td>
<td>0.27, 0.32</td>
<td>0.97, 0.94</td>
<td>0.82, 0.85</td>
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<td>0.75, 0.77</td>
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<td>1.00</td>
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</tr>
<tr>
<td>$(0.1, 0.9)$</td>
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<td>0.82, 0.80</td>
<td>0.68, 0.70</td>
<td>0.99, 0.99</td>
<td>0.10</td>
<td>0.98</td>
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<td>0.76, 0.77</td>
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<td>1.00</td>
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<tr>
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<td>0.42, 0.44</td>
<td>0.58, 0.55</td>
<td>0.82, 0.84</td>
<td>0.93, 0.92</td>
<td>0.24</td>
<td>1.00</td>
<td>1.00</td>
<td>0.27</td>
<td>1.00</td>
</tr>
<tr>
<td>$(0.4, 0.6)$</td>
<td>0.13, 0.15</td>
<td>0.53, 0.55</td>
<td>0.47, 0.45</td>
<td>0.88, 0.89</td>
<td>0.88, 0.87</td>
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<td>1.00</td>
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<tr>
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<td>0.16, 0.15</td>
<td>0.82, 0.83</td>
<td>0.68, 0.67</td>
<td>0.99, 0.99</td>
<td>0.03</td>
<td>0.86</td>
<td>0.98</td>
<td>0.08</td>
<td>0.94</td>
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<tr>
<td>$(0.2, 0.8)$</td>
<td>0.04, 0.04</td>
<td>0.29, 0.28</td>
<td>0.69, 0.67</td>
<td>0.76, 0.75</td>
<td>0.97, 0.97</td>
<td>0.10</td>
<td>0.96</td>
<td>0.99</td>
<td>0.10</td>
<td>0.97</td>
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<tr>
<td>$(0.3, 0.7)$</td>
<td>0.08, 0.08</td>
<td>0.42, 0.40</td>
<td>0.58, 0.59</td>
<td>0.82, 0.82</td>
<td>0.93, 0.93</td>
<td>0.11</td>
<td>0.94</td>
<td>0.97</td>
<td>0.14</td>
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<tr>
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<td>0.88, 0.87</td>
<td>0.88, 0.89</td>
<td>0.10</td>
<td>0.98</td>
<td>0.99</td>
<td>0.09</td>
<td>0.99</td>
</tr>
<tr>
<td>$(0.1, 0.9)$</td>
<td>0.03, 0.03</td>
<td>0.25, 0.24</td>
<td>0.64, 0.67</td>
<td>0.79, 0.78</td>
<td>0.98, 0.98</td>
<td>0.09</td>
<td>0.41</td>
<td>0.77</td>
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<td>0.50, 0.52</td>
<td>0.86, 0.85</td>
<td>0.93, 0.94</td>
<td>0.12</td>
<td>0.57</td>
<td>0.81</td>
<td>0.21</td>
<td>0.78</td>
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<tr>
<td>$(0.3, 0.7)$</td>
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<td>0.58, 0.56</td>
<td>0.40, 0.42</td>
<td>0.91, 0.90</td>
<td>0.88, 0.88</td>
<td>0.13</td>
<td>0.61</td>
<td>0.78</td>
<td>0.13</td>
<td>0.65</td>
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<tr>
<td>$(0.4, 0.6)$</td>
<td>0.23, 0.22</td>
<td>0.70, 0.68</td>
<td>0.31, 0.33</td>
<td>0.94, 0.94</td>
<td>0.81, 0.82</td>
<td>0.19</td>
<td>0.70</td>
<td>0.81</td>
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<td>0.66</td>
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<tr>
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<td>0.79, 0.77</td>
<td>0.98, 0.98</td>
<td>0.24</td>
<td>0.81</td>
<td>0.99</td>
<td>0.31</td>
<td>0.99</td>
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<td>$(0.2, 0.8)$</td>
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<td>0.24</td>
<td>0.89</td>
<td>0.96</td>
<td>0.33</td>
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<td>0.23, 0.21</td>
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<td>0.81, 0.83</td>
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<td>0.96</td>
<td>0.97</td>
<td>0.25</td>
<td>0.93</td>
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</table>

Estimates are based on 100 simulations for each set of parameter values. Bootstrap variances were based on $B = 500$ replicates.
To illustrate the importance of good calibration for estimates of PCF, PNF, and iPCF based on the observed distribution of risks R and outcome data for CRC in AARP women. However, for \( p = 0.10 \), \( \hat{PCF}_R = 0.245 (0.244, 0.246) \), which noticeably overestimated the observed PCF = 0.178. For PNF, a fraction \( \hat{q}_R = 0.898 \) of cases was found in the fraction \( \hat{PNF}_{CC} = \hat{PNF}_{(R,Y)} = 0.797 \) of the population with the highest risk when \( q = 0.90 \), showing an unbiased estimation of PNF. However, only a fraction \( \hat{q}_R = 0.832 \) of cases was found in the fraction \( \hat{PNF}_{R} = 0.711 \) of the population with highest risk when \( q = 0.90 \). Thus, only 83.2% of cases instead of the desired 90% had risks in the highest 71.1% of the population, reflecting poor calibration. Similarly, estimates iPCF \(_R\) were higher than iPCF \(_{CC}\) and iPCF \(_{(R,Y)}\), and iPNF \(_R\) were lower than estimates iPNF \(_{CC}\) and iPNF \(_{(R,Y)}\) (Table 4).

To illustrate the importance of good calibration for estimates of PCF, PNF, and iPCF based on observed risks alone, we recalibrated the model and recalculated these estimates using 5-fold cross-validation. That is, we split the AARP cohort randomly into five equal-sized datasets, and used four of them to recalibrate the model by fitting a logistic regression model to observed CRC outcomes with the risk estimate \( r \) as the independent variable (Cox, 1958). This simple recalibration requires estimating only two parameters, the logistic intercept \( \beta_0 \) and slope \( \beta_1 \). We then used \( \text{logit}(r_e) = \beta_0 + \beta_1 r \) to predict CRC outcomes for women in the remaining fifth of the data, the test set, to estimate the criteria with the recalibrated model. The last column of Table 4 shows averages of estimates of PCF, PNF, iPCF, and iPNF over the five test sets. After recalibration \( \hat{PCF}_R \) was less biased, e.g. \( \hat{PCF}_R = 0.179 \) for \( p = 0.10 \). Similarly, a fraction \( \hat{q}_R = 0.927 \) of cases was found in the fraction \( \hat{PNF}_R = 0.857 \) of women at highest risk.

Table 4. Estimates \( \hat{PCF}, \hat{PNF}, \hat{iPCF}, \) and \( \hat{PNF} \) (with 95% bootstrap confidence intervals in parenthesis) based on the observed distribution of risks \( R \) and outcome data for CRC in AARP women.

<table>
<thead>
<tr>
<th>( p )</th>
<th>PCF*</th>
<th>PCF (_R)</th>
<th>PCF (_{CC})</th>
<th>PCF (_{(R,Y)})</th>
<th>PCF (_R)</th>
</tr>
</thead>
<tbody>
<tr>
<td>0.10</td>
<td>0.178</td>
<td>0.245 (0.244, 0.246)</td>
<td>0.178 (0.155, 0.202)</td>
<td>0.178 (0.152, 0.205)</td>
<td>0.179</td>
</tr>
<tr>
<td>0.20</td>
<td>0.313</td>
<td>0.415 (0.413, 0.416)</td>
<td>0.313 (0.284, 0.342)</td>
<td>0.311 (0.277, 0.345)</td>
<td>0.307</td>
</tr>
<tr>
<td>0.30</td>
<td>0.423</td>
<td>0.551 (0.549, 0.552)</td>
<td>0.420 (0.387, 0.452)</td>
<td>0.420 (0.377, 0.462)</td>
<td>0.418</td>
</tr>
<tr>
<td>0.40</td>
<td>0.549</td>
<td>0.663 (0.662, 0.664)</td>
<td>0.547 (0.515, 0.579)</td>
<td>0.547 (0.500, 0.594)</td>
<td>0.518</td>
</tr>
</tbody>
</table>

The corresponding observed proportion of cases PCF* found among the fraction \( q \) of the AARP population at highest risk and the proportions \( p_R \) and \( p_{CC} \) of cases found among the fractions \( \hat{PNF}_R \) and \( \hat{PNF}_{CC} \) of the AARP population at highest risk are also shown. \( \hat{PCF}_R \) and \( \hat{PNF}_R \) are based means over five test sets of the model after recalibration using 5-fold cross-validation.
when \( q = 0.90 \), reflecting improved calibration of \( R_c \). Estimates \( \hat{iPCF}_{R_c} \) and \( \hat{iPNF}_{R_c} \) were also noticeably closer to \( \hat{iPCF}_{CC} \) and \( \hat{iPNF}_{CC} \).

8. DISCUSSION

We proposed two new criteria for model evaluation, iPCF and iPNF, respectively, which lessen the dependency of earlier criteria, PCF and PNF, on prespecified thresholds. PCF (\( p \)) = \( 1 - G \circ F^{-1}(1 - p) \) resembles the ROC value, which can be expressed as ROC (\( p \)) = \( 1 - G \circ K^{-1}(1 - p) \) (Huang and Pepe, 2009). Similarly, iPCF that also is based on comparing the distribution of risk in cases to the distribution of risk in the whole population instead of in non-cases, relates to the AUC, the partial area under the ROC curve, pAUC, or more generally, to the weighted area under the ROC curve (Li and Fine, 2010). For rare diseases, they tend to be very similar, but derivations of the asymptotic properties for criteria based on PCF and PNF are more involved, as unlike the estimates of the ROC curve and the (partial) AUC, the risks in the population and in cases are not independent. The comparison of risk in cases to non-cases is appropriate for diagnostic tests that are applied in a clinical setting. However, for risk models that may be used to identify high-risk individuals for screening or for assessing the impact of a screening program in a population, criteria based on comparing the risk of cases to the risk in the whole population are more relevant (Pharoah and others, 2002).

While decision making based on risk models for public health applications ultimately needs to incorporate cost considerations, the proposed criteria can aid in the initial assessment of the feasibility of a screening or intervention program. For example, assume that one can only afford to screen 10% of a population. If a particular model has a low PCF or high PNF, targeting those at highest risk based on that model will have limited preventive impact. In contrast, if a model has a high PCF or a low PNF, then a targeted screening program may identify a large proportion of the disease and reduce costs and the burden of screening. A more complete understanding is provided by iPCF and iPNF, which display the proportion of disease accounted for by cumulative proportions of individuals in the population ranked from the lowest to highest risk.

The new criteria are also useful for comparing two risk models evaluated on the same dataset. A test for comparing two models based on PCF had comparable power to a test based on pAUC. However, a test for model comparison based on iPCF had significantly better power than a test based on PCF, while the tests based on PNF and iPNF had similar power.

We also studied estimates of PCF, PNF, iPCF, and iPNF when either risk estimates alone, or risk estimates and outcomes in a case–control study with known prevalence or in a cohort study are available. Estimates that also used outcome data were less efficient than estimates that were based on only observed risks and the assumption that the model was well calibrated. The efficiency gain comes from the fact that, for a well-calibrated model, knowing \( F \) implies knowing \( G \), the distribution of risk in the cases. All the observed risks in a population are thus used to estimate \( G \). When one estimates \( G \) from the risks in observed cases in a cohort, i.e. based on \((R, Y)\), the effective sample size is much reduced, leading to substantial losses in efficiency. However, as also highlighted by our real example, estimates of PCF, PNF, iPCF, and iPNF based on \( R \) alone are biased when the model is not well calibrated, and model comparisons can be misleading. In practice, if outcome data are not available, one is forced to use estimates such as \( \hat{iPCF}_{R} \). If outcome data are available, one can compute \( \hat{iPCF}_{(R, Y)} \). If there are large discrepancies, one must suspect miscalibration and rely on \( \hat{iPCF}_{(R, Y)} \). We thus recommend using estimates of the criteria based on \( R \) alone, but comparing them to estimates that also use \( Y \) to check unbiasedness.

SUPPLEMENTARY MATERIAL

Supplementary material is available at http://biostatistics.oxfordjournals.org.
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